# Panasonic

CE
Conforming to
EMC Directive

Certified by NRTL
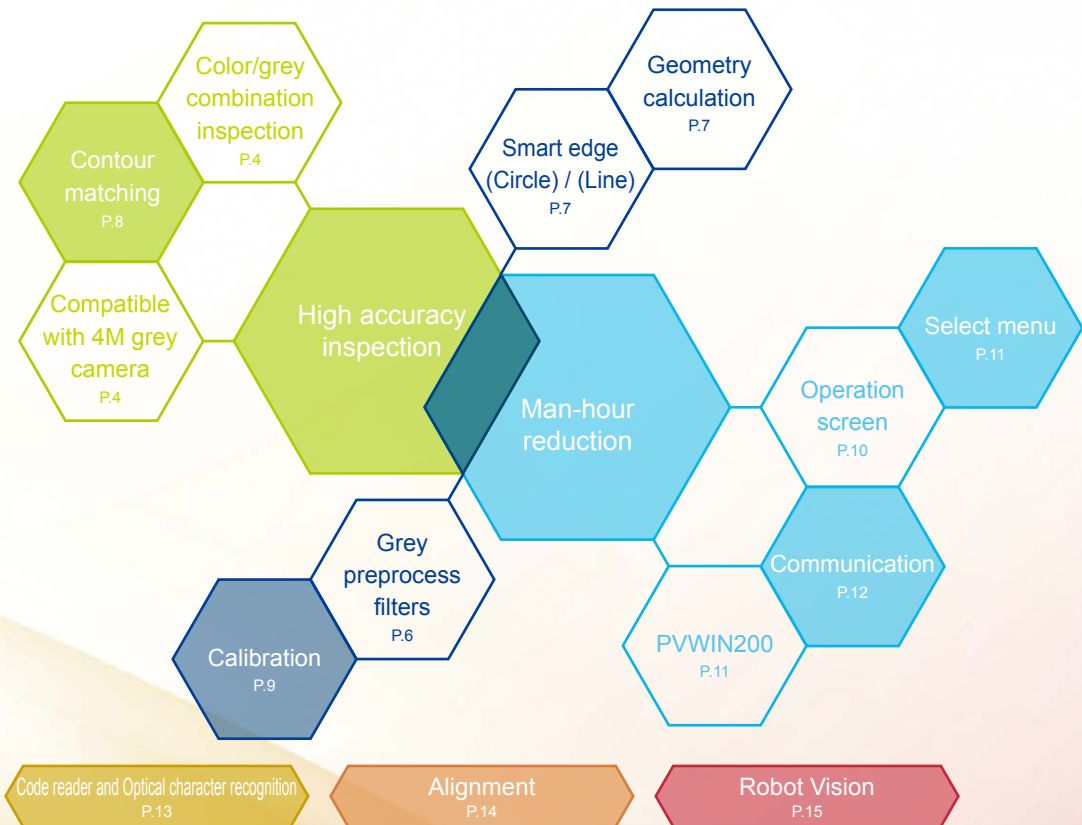(**ANPV0202ADP** only)

## High End Performance in a Compact Body

# COMPACT & **HIGH SPEC**
ULTRA HIGH SPEED VISION SYSTEM IMAGECHECKER PV200 SERIES

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ULTRA HIGH SPEED VISION SYSTEM IMAGECHECKER PV200 SERIES

# IMAGECHECKER
# PV200

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# Improved inspection reliability
# while reducing engineering time

Image processing with impressive accuracy and performance can now be achieved

while requiring a surprisingly low implementation and programming time.

The new ideal machine is a color/grey combination type.

# Hardware

Color and grey images can be simultaneously captured for inspection.

In addition, the "3+1" Quad processor provides ultra-high speed parallel processing, significantly reducing the inspection time.
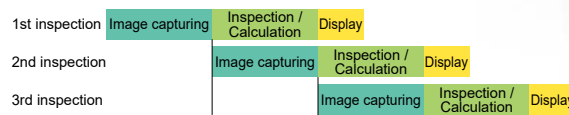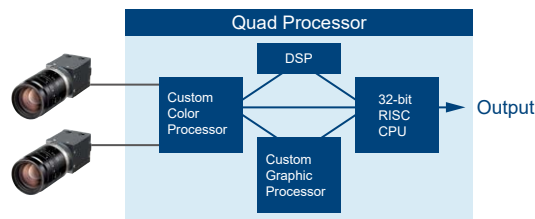
Features are condensed into the ultra-compact body guaranteeing outstanding usability.

50 mm / 1.97 in
116.5 mm / 4.59 in
148 mm / 5.83 in

DIN-rail mountable

## ◎ Quad processor, DSP processing & Pipeline processing

"3 + 1" Quad processor for high speed processing

Consists of a processor exclusively for image capture and transfer, a high-speed RISC-CPU, image-processing DSP, and a processor exclusively for display processing

- Pipeline processing by the Quad processor enables concurrent operation of the image capture process and inspection process.
- Ease of operation is increased, because data R (read) / W (write) (see page 10) and display layout switching operations are possible in the RUN mode.
- DSP processing: High-speed DSP is a processor dedicated for realtime image and grey pre-process filtering.
- High reliability, fan-less, standalone hardware

**Quad Processor**

DSP
Custom Color Processor
32-bit RISC CPU
Custom Graphic Processor
Output

| 1st inspection | Image capturing | Inspection / Calculation | Display |
| 2nd inspection | | Image capturing | Inspection / Calculation | Display |
| 3rd inspection | | | Image capturing | Inspection / Calculation | Display |

With pipeline (parallel) processing, image capturing and inspection can execute at the same time.
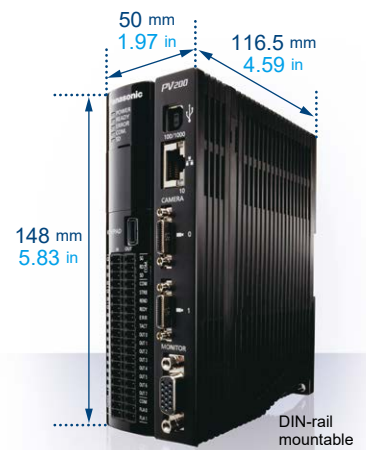
## ◎ Two cameras, including a combination of color and grey cameras, can be simultaneously connected.

High definition color and grey cameras can be simultaneously connected. Inspections with color and grey images can be conducted concurrently.
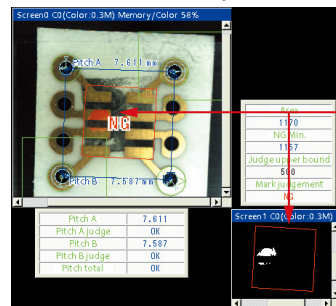
Color images clearly show red bad marks, which are difficult to detect with grey images.

## ◎ Color / Grey combination inspection system

High accuracy inspection

Grey image
Color image

Grey conversion
Color extraction

Preprocess

Grey preprocess (Can be enabled/disabled)
Grey preprocess (Can be enabled/disabled)
Grey preprocess (Can be enabled/disabled)

Available checkers

| Binary window | Smart matching | Connector (grey edge) |
| Grey window | Flaw detection | Smart edge (circles) |
| Grey edge | Connector (binary window) | Smart edge (line) |
| Feature extraction | Connector (grey window) | etc. |

Color window

### Grey conversion

Highly flexible grey conversion is possible, because each coefficient can be freely specified for each RGB value of a color image.

Color image → Grey conversion

Foreign substance   Hair
Foreign substance   Hair

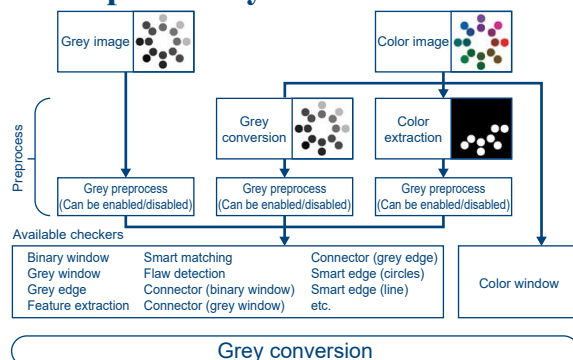## ◎ Camera selections

High accuracy inspection

Seven types of cameras, including a 4M grey camera, are available with the system.
0.3M compact camera has been added to the product line-up. The body is approximately 20 mm 0.79 in more compact lengthwise compared to previous 0.3M grey cameras.
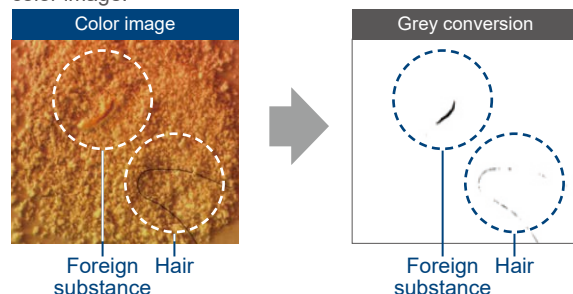
**Color cameras**

new *1 *2

[ 0.3M pixel ]   [ 0.3M pixel compact ]   [ 2M pixel ]

**Grey cameras**

*2   *3

[ 0.3M pixel ]   [ 0.3M pixel compact ]   [ 2M pixel ]   [ 4M pixel ]

*1 The main body firmware Ver.1.50 or later is required. Software can be downloaded from our website.
*2 A dedicated cable is required for connecting.
*3 The 4M camera cannot be used in combination with another type of camera.

### Color window

The maximum, minimum, average, and deviation of RGB values can be obtained. Results can be used for numerical calculations and outputted externally.

| | Max. | Min. | Judge | Ave. | Judge | Std. Devi. | Judge |
|---|---|---|---|---|---|---|---|
| R | 255 | 71 | OK | 145 | OK | 39.370 | OK |
| G | 224 | 22 | OK | 53 | OK | 17.694 | OK |
| B | 158 | 41 | OK | 71 | OK | 14.592 | OK |

| | Max. | Min. | Judge | Ave. | Judge | Std. Devi. | Judge |
|---|---|---|---|---|---|---|---|
| R | 255 | 119 | OK | 224 | OK | 31.705 | OK |
| G | 211 | 40 | OK | 89 | OK | 21.201 | OK |
| B | 182 | 77 | OK | 113 | OK | 14.148 | OK |

### Color extraction

Colors in different color phases can be simultaneously extracted and inspected by using one inspection checker.

Color image → Color extraction
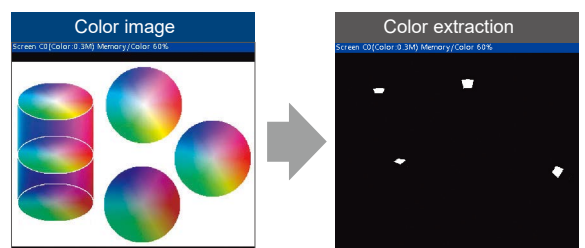
Purple and red orange is extracted.

# ○ Branch execution/Designated execution

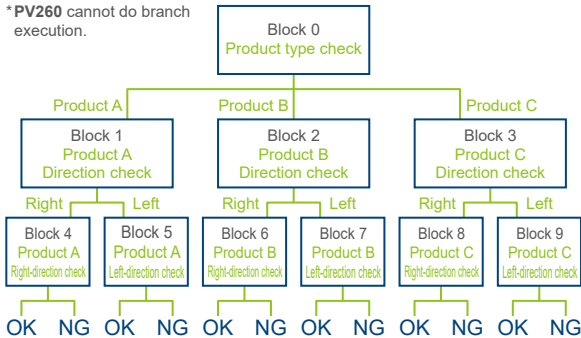**Man-hour reduction**

The inspections can be quickly changed to meet multiple product types or various conditions.
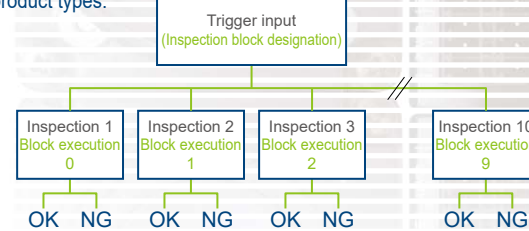
## Branch execution

Up to nine branches can be set to choose an inspection to be executed depending on the test results.

*PV260 cannot do branch execution.

Block 0
Product type check

Product A — Product B — Product C

Block 1
Product A
Direction check

Block 2
Product B
Direction check

Block 3
Product C
Direction check

Right — Left

Block 4
Product A
Right-direction check

Block 5
Product A
Left-direction check

Block 6
Product B
Right-direction check

Block 7
Product B
Left-direction check

Block 8
Product C
Right-direction check

Block 9
Product C
Left-direction check

OK NG  OK NG  OK NG  OK NG  OK NG  OK NG

## Designated execution

After trigger signal is applied, up to ten different inspections can be executed immediately. This minimizes the time spent on switching product types.

Trigger input
(Inspection block designation)

Inspection 1
Block execution
0

Inspection 2
Block execution
1

Inspection 3
Block execution
2

Inspection 10
Block execution
9

OK NG  OK NG  OK NG  OK NG

Inspection result of each block is stored until the next execution.
A dedicated application can be created by controlling the block execution timing externally.
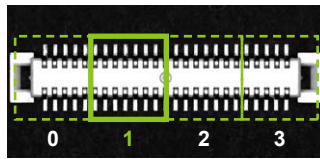
### Applications

**Case 1** One work is moved and inspected numerous times then given a total judgment (inspection of target using split captures in order to obtain necessary resolution).
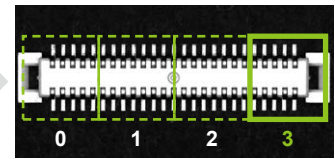
**Total judgment result output with last block**

Block 0 (Inspection of area on furthest left)

0  1  2  3
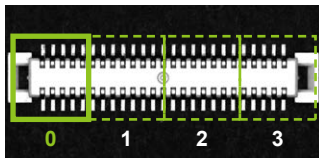
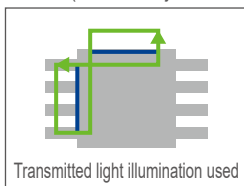Block 1 (Inspection of next area)

0  1  2  3

Block 3 (Inspection of last area and total judgment)

0  1  2  3

**Case 2** Imaging conditions are changed, work is inspected numerous times, and total judgment is made (lighting of light source is controlled by a PLC).

**Result of Block 0 is used to inspect at Block 1.**
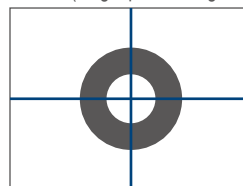
Block 0 (Position adjustment of work)

Transmitted light illumination used

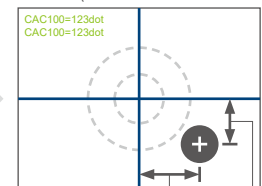Block 1 (External inspection)

Reflected light illumination used
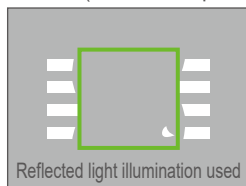
**Case 3** Simple alignment

**Result of Block 0 is used to inspect at Block 1.**

Block 0 (Target position registered)

Block 1 (Shift amount calculated)

CAC100=123dot
CAC100=123dot

Shift amount X   Shift amount Y

# ○ Inspections of a variety of points of a variety of product types

■ **Data for up to 256 types can be saved in the built-in memory alone, and 25,600 types with an SD memory card inserted.**

■ **Maximum registrable number of checkers: 1,000 checkers / type**

| Checker types | Line | Binary window | Grey window | Binary edge | Grey edge |
|---|---|---|---|---|---|
| | Feature extraction | Smart matching | Contour matching | Flaw detection | Color window |
| | Three connectors (binary window, grey window, and grey edge) | | | Smart edge (circles) / (line) | |

A total of 15 types

■ **Maximum registrable number of templates: 2,000 templates**

■ **Maximum available number of numerical calculation formulas: 1,000 formulas / type**

A variety of operators for numerical calculation are available: Four fundamental operations (+, -, x, ÷), bracket operation, trigonometric function (14 types), comparison function (6 types), mathematical function (15 types), geometric function (18 types), and statistical function (18 types).

■ **Execution blocks: 10 blocks / type**

■ **Position adjustment: 1,000 checkers / type, Area adjustment: 1,000 checkers / type**
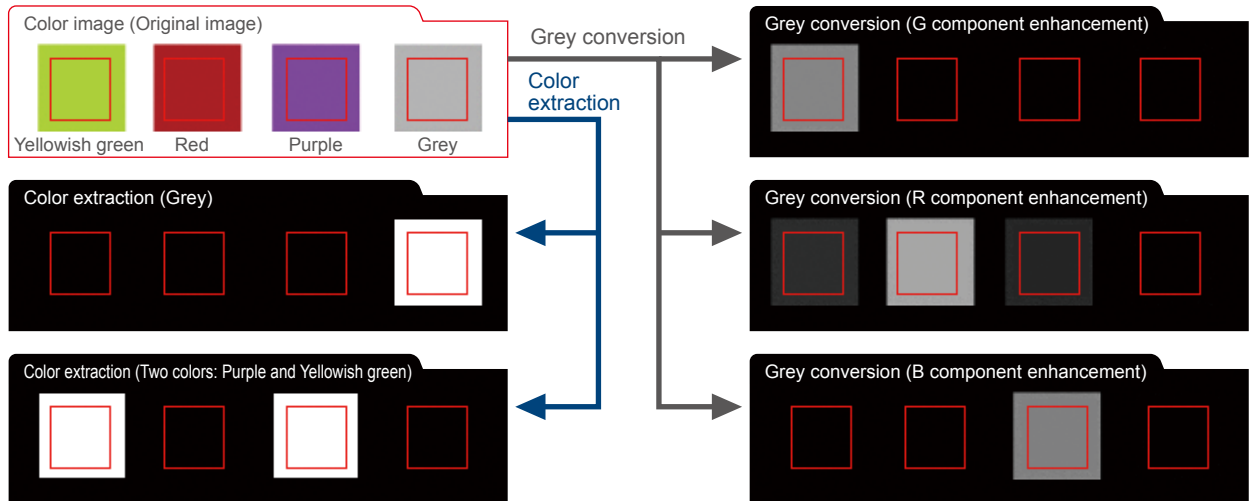
# Preprocessing

## ◎ Grey conversion / Color extraction

• Grey conversion: Max. 16 groups/camera

The conversion coefficients are set for the color image RGB greyscale value and the image is converted to grey. Each RGB coefficient can be set freely (-1,000 to +1,000). This makes it difficult for the inspection to be affected by color changes, such as by the removal of low saturation (low coloration) or non-color parts and by target color enhancement, caused by lighting fluctuations.

• Color extraction: Max. 128 colors/type (one camera, expansion mode)

Utilizing the parameters H (Hue), S (Saturation) and V (Value), which resemble the way humans perceive differences in color, multiple colors (max. 128 colors) can be extracted simultaneously.



## ◎ Grey preprocess filters

21 types of grey preprocess filters are available. Reliable inspections are possible even under non-uniform lighting conditions or in the case of images with noise.

• Preprocess filters: 21 types   • Preprocess groups: Max. 16 groups/camera   • Preprocess steps: Max. 10 steps/group

| Main purpose | Filter name | |
|---|---|---|
| Flaw detection | • Tophat<br>• Dynamic | • Grey difference |
| Noise removal | • Dilation<br>• Erosion | • Erosion → Dilation<br>• Dilation → Erosion |
| Image adjustment | • Rotation<br>• Reflect | |

| Main purpose | Filter name | | |
|---|---|---|---|
| Contour enhancement | • Sobel<br>• Prewitt | • Laplacian<br>• Edge extraction X | • Edge extraction Y<br>• Sharpen |
| Blurring | • Median<br>• Smoothing | | |
| Contrast enhancement | • Auto correction<br>• Grey cut | • Area averaging<br>• Correction settings | |

| Application example | Original image | Processed image |
|---|---|---|
| Checking container lids for adhesion of foreign substances<br>**Filter used**<br>**[ Tophat ]** | | |
| Checking films / sheets for scratches / wrinkles<br>**Filter used**<br>**[ Grey difference, Area averaging ]** | | |
| Detecting dirt on transparent sheets<br>**Filter used**<br>**[ Dynamic ]** | | |

| Application example | Original image | Processed image |
|---|---|---|
| Extracting printed characters (deleting the background)<br>**Filter used**<br>**[ Dynamic ]** | | |
| Checking the inside of containers for adhesion of foreign substances<br>**Filter used**<br>**[ Grey difference, Tophat ]** | | |
| Checking sintered parts for breaks / cracks<br>**Filter used**<br>**[ Grey difference, Tophat ]** | | |

# Checker Functions

## ⭘ Smart edge (Circle)/(Line)

**Complicated inspection processes can be easily performed with highly accurate measurements.**

A function for accurate approximation of circles/lines
This function detects a maximum of 3,000 edge points for a line and 3,600 for a circle in one area, dramatically improving the accuracy of the dimension and position measurements.

**Operation principle**

1. A Grey edge scanning area is created, and edge points in the area are searched to detect the contour of the object.

2. Virtual circles and approximate straight lines can be identified with a high degree of accuracy based on the target edge points.

3. Pass (OK) /fail (NG) evaluations are made based on the measured values (radius, diameter, and width), deviations, circularity, straightness, and the number of edges outside the area.
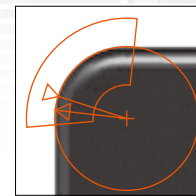
### Smart edge (circle) setting example
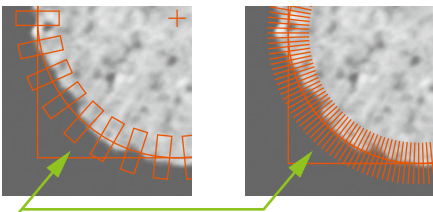
One cell can have a minimum width of one pixel (linear scanning), and a maximum of 3,600 cells can be set per 0.1°.
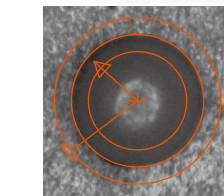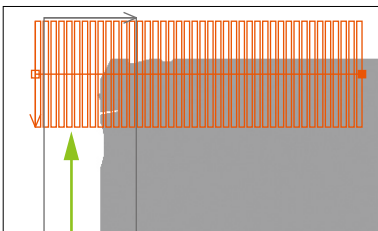
The center of the virtual circle, radius, diameter, circularity, and ring width can be measured.
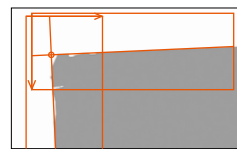
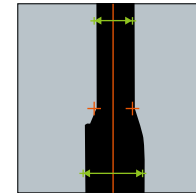The center and radius of the corner are measured.

### Smart edge (line) setting example
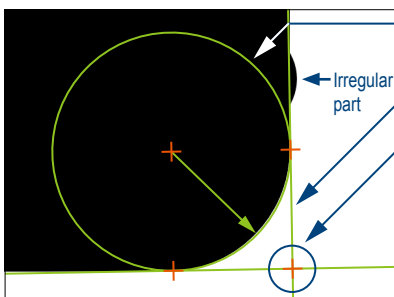
A maximum of 3,000 cells can be set.

The influence of surface imperfections is eliminated to accurately detect the target straight line by approximation.

Imperfections along a target sample can be analyzed for maximum and minimum values.

## ⭘ Geometry calculation

Virtual circle
Irregular part
Approximate straight line
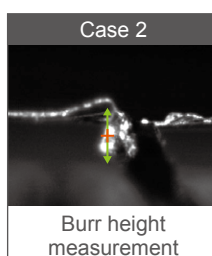Intersection of two lines

**Distances, intersections, and median lines can be detected.**

This function detects the distance between two points, the intersection of two lines, the median line of two lines, the perpendicular distance, and an approximate ellipse. In combination with Smart edge (circle) / (line), this function recognizes the object as a geometric figure, allowing the coordinates, distances, dimensions, and angles to be obtained without preparing calculation formulas.
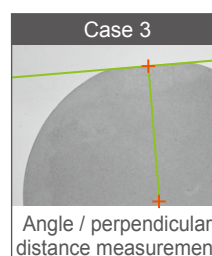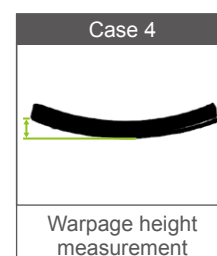
**Applications**
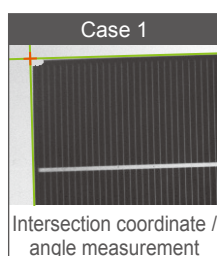
| Case 1 | Case 2 | Case 3 | Case 4 |
|---|---|---|---|
| Intersection coordinate / angle measurement | Burr height measurement | Angle / perpendicular distance measurement | Warpage height measurement |

# Checker Functions

## ⬡ Matching

By using the **PV200** series matching function, highly accurate detection is possible using two means of matching that take into account the characteristics of the target object and the process environment.
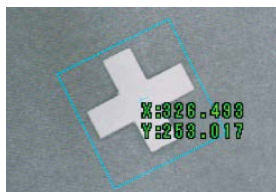
### Smart matching

**Pattern search**

Through means of a unique normalization process, stable detection can be achieved with reduced influence from grey fluctuations.
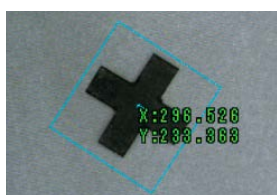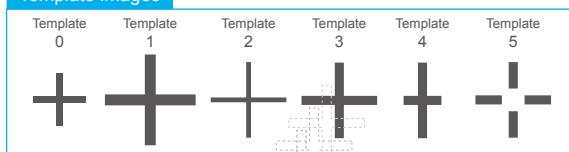
**Detects even with low-contrast images**

**Detects even with negative images**

#### Selection possible among multiple templates

A high-precision inspection is possible by searching a maximum of 64 templates in the same search area to detect a result with the highest correlation.

**Template images**

| Template 0 | Template 1 | Template 2 | Template 3 | Template 4 | Template 5 |

Object of search

After searching all templates, Template 3 with the highest correlation is used for detection.

#### Extraction of deviating portion using pattern difference

Based on the position information obtained by the matching function, the registered object and detected object are overlapped and compared on a pixel-by-pixel basis. Any pixels with a difference in brightness over a certain level are detected. The area value of such pixels can then be used to make pass/fail evaluations.

Template

Detected by matching

Difference detection result
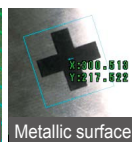
Detects different portions only
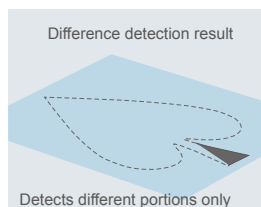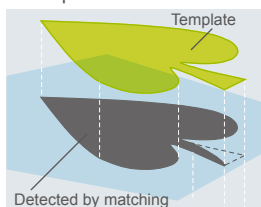
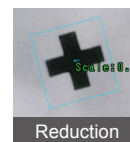### Contour matching

**Contour search**

A template is created from the contour information (object) obtained from the grey change points (edge points), which means stable detection can be achieved without being influenced by the object shape or changes to the background.

Background change | Metallic surface

**Detects even if background changes.**

Even if all of detected target object is registered, detection will be stable regardless of the state of the background.
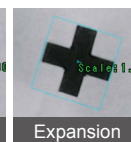
Reduction | Expansion

**Detects even if the magnification changes (±10 % max.)**

The same template can be used for detection even if in processes where the distance between the work and the camera changes.
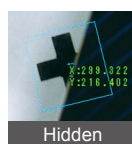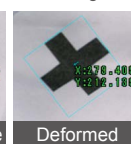
Hidden | Overlapped

**Detects even if target object is hidden**

Stable detection is possible even if part of the object being detected is deficient.

Mirrored surface | Deformed

**Detects even with noise on the target object**

Stable detection is possible even if the part of the object being detected changed due to a limitation in the lighting or inspection process.

### Common template

Register to smart matching

Register to contour matching

- When a common template is used, the information of all checkers that use the same template will be updated with the switch of one template. Compared to the setting of templates individually, time is saved by reducing repetitious work and operational mistakes are prevented.
- Also, since it is not necessary to register the same template more than once, space for holding templates on the **PV200** series can be saved.
  Images registered as common templates can be used for both smart matching and contour matching.

## ● Flaw detection  High accuracy inspection | Man-hour reduction

This function is ideal for critical appearance inspections, such as scratches, stains, chipped edges, burrs, and other flaws in objects. The inspection is carried out by comparing a target's greyscale image with neighboring parts, which helps in the detection of minor scratches, stains, and chips.

Chipping and burrs

Chipping and burrs

**Scanning conditions**

[Line]

256 cells max.

[Plane]

256 cells

65,536 cells max.

The micro cell area (a minimum of 3x3 pixels) is continuously generated, and defects are detected based on the amount of change in the density in the inspection area.

**[Circles, Ellipses, and Partial arcs]**

0.1° pitches

256 cells

3,600 cells max.
* Minimum size of one cell: 3x3 pixels
* A setup is possible in the minimum 0.1° pitch.
  [For circles (360°) inspection]

## ● Connector checker  High accuracy inspection | Man-hour reduction

Setup for connector inspection has been burdensome up to now. Now inspection can be accomplished by creating one area. This enables a great man-hour reduction.
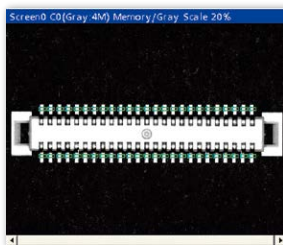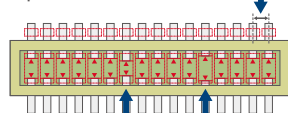
**Inspection example**

Screen0 C0(Gray 4M) Memory/Gray Scale 20%

**Pin pitch inspection**

This function measures the distance between the edges of each pair of adjacent pins and evaluates the results based on the preset upper and lower limits. Data of the "start point", "end point", and "number of pins" should be input.

**Pin coplanarity inspection**

This function detects raised pins. In the same way as the pin pitch inspection, setting simply adjusts the position using one checker and then inputting the number of pins.
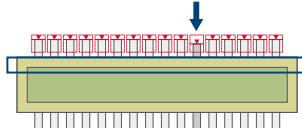
**Inside pin gap inspection**

This function inspects the gap between facing ends of pins. Simply input the number of pins. The upper and lower limits of the gap can be set.

## ● Coordinate calibration

Setting and calculation is possible, linking the camera image with the actual dimensions.

**Link two images**

Global coordinates between two cameras are generated and both results are quoted to enable direct calculation.

Camera 1 = 0.3M camera

Camera 0 = 2M camera
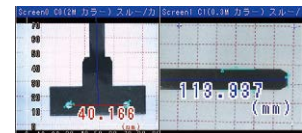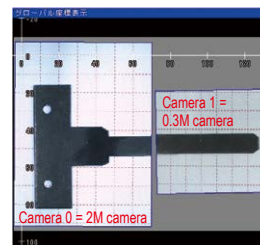
Calculation is possible mixing the separate detected data by two cameras.

**Dynamic calibration**

Conveyance differences arising during stage and index conveyance are adjusted each time to enable stable measuring of the work dimensions.

Reference point 2: Matching

Reference point 1: Matching
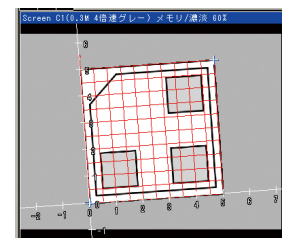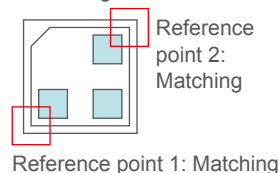
## ● Our unique algorithm for ultra high speed processing

Parallel processing by Quad processor and our unique algorithm ensure outstanding ultra high speed inspections.

[Execution processing speed]  Unit: msec

| Checker fuctions*1 | 640 × 480 | 1,600 × 1,200 | 2,048 × 2,048 |
|---|---|---|---|
| Binary window | 0.5 | 1.7 | 3.3 |
| Grayscale window | 0.4 | 1.5 | 2.9 |
| Binary edge | 2.1 | 11.3 | 23.7 |
| Grayscale edge | 8.7 | 54.0 | 117.2 |
| Feature extraction | 1.1 | 3.8 | 6.9 |
| Smart matching*2 | 5.0 | 32.3 | 63.5 |
| Contour matching*3 | 26.4 | 111.3 | 329.4 |

*1: The processing speed above is a reference value based on default settings.
    Processing speed vary depending on the image being inspected.
*2: Template: 128 x 128, Without rotation
*3: Template: 128 x 128, Rotation: ±30 °, Scale: ±5 %
*4: When using a color camera.

[Execution processing speed]  Unit: msec

| Filter functions | 640 × 480 | 1,600 × 1,200 | 2,048 × 2,048 |
|---|---|---|---|
| 5 x 5 Dilation | 0.8 | 3.7 | 7.6 |
| 5 x 5 Erosion | 0.8 | 3.7 | 7.6 |
| 5 x 5 Smoothing | 1.2 | 5.8 | 13.1 |
| 5 x 5 Edge extraction X | 0.8 | 3.3 | 6.6 |
| 5 x 5 Edge extraction Y | 0.8 | 3.3 | 6.8 |
| 5 x 5 Prewitt | 1.9 | 9.9 | 21.5 |
| 5 x 5 Sobel | 1.9 | 10.5 | 21.7 |
| Image rotation | 1.9 | 11.5 | 24.8 |
| Grey conversion*4 | 1.2 | 5.1 | – |
| Color extraction*4 | 0.5 | 2.4 | – |

# Interface

## ⭕ Operation screen  *Man-hour reduction*

The **PV200** series has been designed to simplify implementation in both pre-production and post-production.
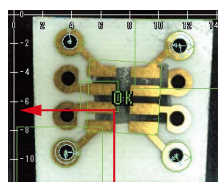


**Unit conversion axes**

X and Y axes indicate the scale converted into the actual dimensions. (Separately settable for each camera)

---
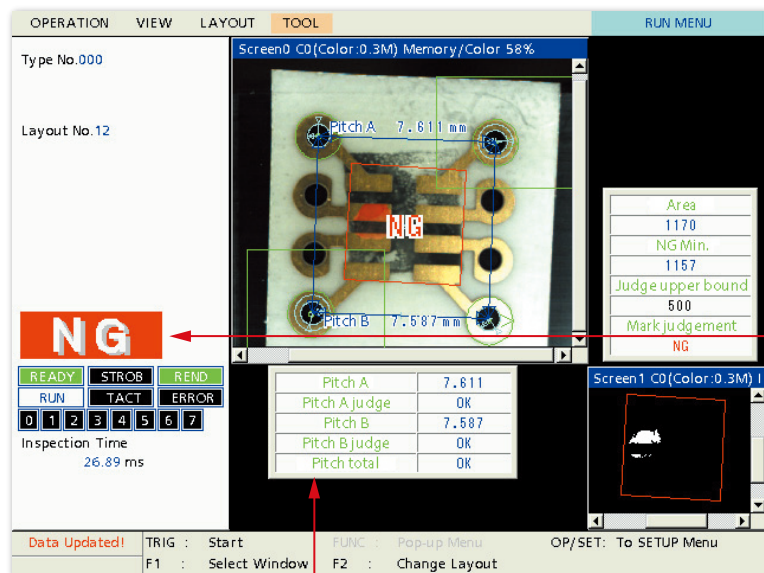
### Data R (Read) / W (Write) function

Program modifications can be quickly made in the RUN mode without replacing the program or switching to the setting screen. This is useful in cases where changes to the inspection area and pre-processing parameters must be made after the program has been finalized.

[Modification examples]



Change the X coordinate of the start point.



Change the pre-processing filter setting.

---

### Splash screen

The splash (startup) screen can be changed to an original screen, such as a screen suitable for the user's equipment or a screen including a brand logo. (A bitmap with a maximum size of 640 x 480 pixels)

---

### Operation customization by external signal

The **PV200** series is equipped with a total of five points for ASSIGN and EXTRA signals, which allow you to customize the allocations of tasks, such as layout switching, image data output and screenshot printing.

---

### Customizable Display

■ **Character / Figure drawing**
A function for drawing text (multi-lingual), measured values, cross marks, arrow marks (dimension lines), rectangles, and ellipses. This function allows drawn items to be displayed following the calculation results or detected positions. It is also possible to specify the character size, fill regions and switch the drawn item colors or turn on/off the display of the items according to the pass/fail check results.

■ **Marker function**
A straight line, rectangle, circle, ellipse, and cross line can be displayed at any position. The display position can be specified by using external signal.

■ **Layout**
The VGA screen (640 x 480 pixels) can display two images and two pages of the Data R/W screen. Layouts can be customized and up to 16 patterns can be registered. They can be switched in accordance with the situation using either the keypad or external signals.
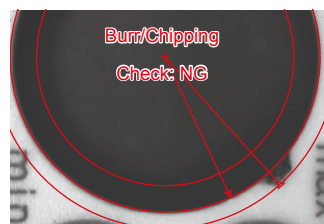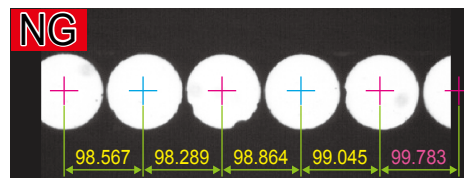
## ◎ Setup screen

### Select menu

By registering to the menu list any item you prefer from the items in the setup screen, you become able to perform operations directly, verify settings, and make changes.
• Improve operability by registering to the menu those functions you use a lot.
• Prevent operation mistakes by registering to the menu those functions that are okay to change.

Checker parameter registration
Only the set value and result are displayed when a checker parameter is chosen.
*Parameters other than those items chosen are not displayed.
Number of registrations:
max. 50 pages/product type (16 items/page)

### Password protection

Setting a password prevents the careless switching to the setup screen. The password can have a maximum of 15 digits (from 84 alphanumeric and symbol characters). By joint use with the Select Menu, it is possible to distinguish between operator and administrator use.
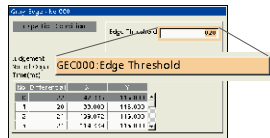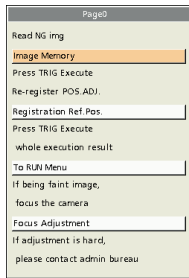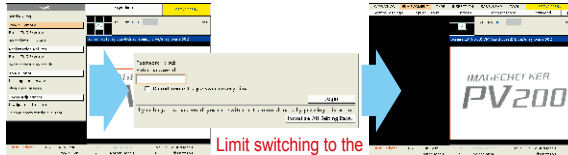
Limit switching to the regular setup menu.

Select Menu

Regular setup menu

### Collective moving of inspection areas

This function is essential to simultaneously move multiple inspection areas for the purpose of fine adjustment of the target position. The areas can be chosen by camera, position correction group, or inspection checker type.

Collective moving
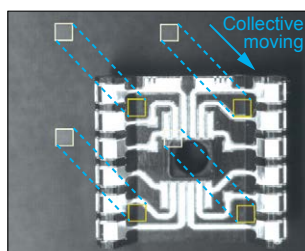
## ◎ PVWIN200 setup software

### User-friendly drag-and-drop operations

Drag the target image and drop it onto a **PVWIN200** screen to start the operation. The guidance by the navigation view icons will help you set the inspection conditions.

Simulation cycle

Download PVWIN for free from our website.

### Checker list

The checker list shows the on/off state of each inspection function and the inspection results so that users can check the program outline. It is possible to jump to the setting screen for a selected function and edit the settings.

Check on the checker list

Jump to the checker setting screen
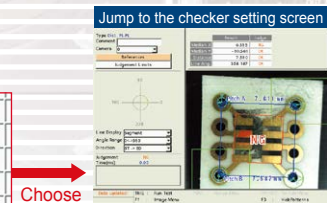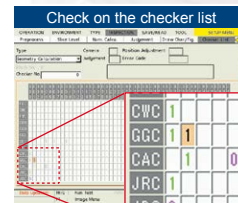
Choose and jump

### Histogram

In the image preprocessing and the binarization setting screens, both the original image and its histogram are displayed as guidance for processing

Thumbnail of the original image
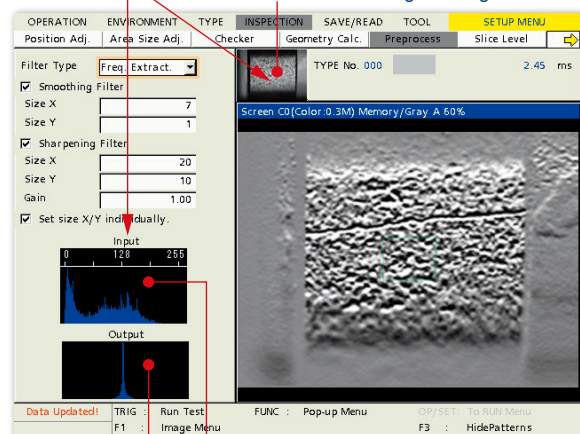
After processing    Before processing

### Setting help

Various functions are built in that are useful when installing the **PV200** series at the worksite.

Setting help function

- Focus adjustment
- Communication test
- Aperture adjustment
- Parallel I/O test
- Grey data analysis
- Image capture delay adjustment

### Simulation cycle for debugging

The continuous simulation and data logging functions facilitate setting data corrections and verifications. The export function allows you to manage the setting data change history.

Can be switched to the screen displaying "NG" items only

PV200 setup software
IMAGECHECKER
*PVWIN200*

# Interface

## ◯ Communication ⬡ Man-hour reduction

---
### PLC communication
---

By simply setting the register address of the PLC or other equipment you are using with the device, it is possible to receive **PV200** series results and perform command operations.

| Result output | Command processing |
|---|---|

By using the PLC communications function, the **PV200** series results can be written directly to the PLC register without a communications program.
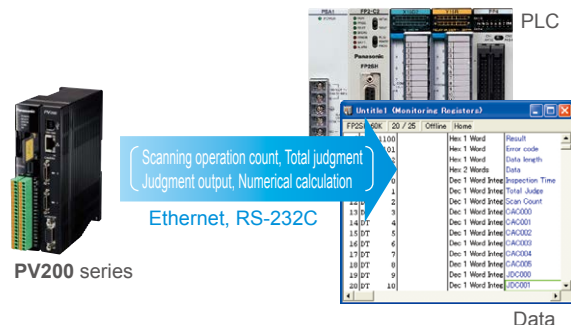
**PV200** external command control is possible by operating the PLC register values without a communications program.

PLC



Scanning operation count, Total judgment Judgment output, Numerical calculation

Ethernet, RS-232C

**PV200** series

Data

PLC

Contact

Command read

Response write

**PV200** series
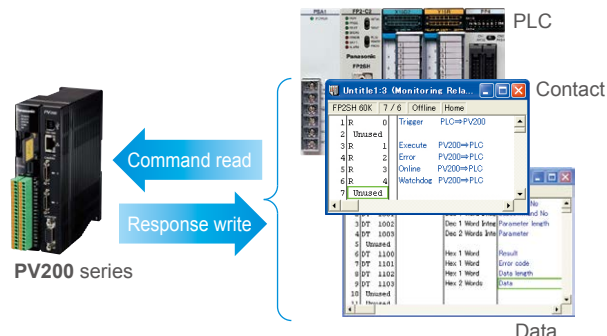
Data

---
### High-speed communications and storage (Built-in memory / Ethernet / SD memory card)
---

### Inspection and judgement result data output

■ Compatible with parallel I/O , RS-232C (115.2 kbps), Ethernet (Gigabit). The RS-232C PLC communications are now compatible with Modbus RTU.

### Image data

■ Up to 312 images captured by the 0.3M camera, 39 images captured by the 2M camera and 14 images captured by the 4M camera can be stored in the built-in memory in real time (without increasing the processing time).[*1]

■ A 32 GB SD memory card can store a maximum of about 90,000 images captured by the 0.3M camera, about 16,500 images captured by the 2M camera or about 7,600 images captured by 4M camera. [*2]

■ The Gigabit Ethernet LAN port allows image transfers at three to five times the speed of 100-Megabit Ethernet. Via this port, one image captured by the 0.3M camera can be transferred in 80 msec.[*3]

| Conventional model (**PV310**) | Transfer time |
|---|---|
| 100-Megabit Ethernet | |
| **PV200** | Transfer time |
| Gigabit Ethernet | |

*1: When one camera is connected.   *2: Color camera images: Bayer format
*3: Depends on the connected equipment.

---
### Multiple simultaneous output to external devices.
---

Judgement results and numerical result data can be simultaneously output to RS-232C and Ethernet interfaces, and to SD/SDHC memory cards. For example, the data for traceability and inspection control can be simultaneously output.

Ethernet

HUB

General use results output

Data transfer Image storing (for traceability) *4

| Destination | Operation | Protocol |
|---|---|---|
| ☐ Serial | Sync. | General Com. |
| ☑ Ethernet | Sync. | PLC Com. |
| ☑ Ethernet | Sync. | General Com. |
| ☐ SD card | Sync. | General Com. |

PLC communications (RS-232C is also selectable)

Data transfer (for inspection control and display)

PLC
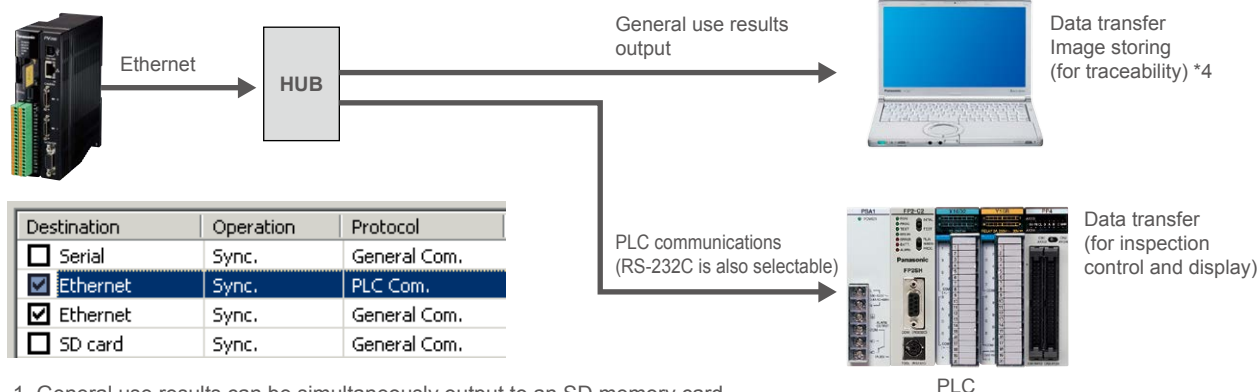
1. General use results can be simultaneously output to an SD memory card, RS-232C and Ethernet interfaces.
2. Ethernet can be used at the same time for output of general use results and PLC communications.

*4: The free software "**Image Receiver for PV**" is used.

**Machine Vision System**

# Solutions for Optical Character Recognition (OCR) and 1D / 2D Code Reading (CR)

## All-in-one model featuring image processing, optical character recognition (OCR) and code reading (CR) functions

- Compatible with a wide variety of cameras ranging from 0.3M to 4M pixels
  Reliable character extraction achieved by the color / gray combination function
- The optical character recognition (OCR) can read up to 80 characters. [Capable of case-sensitive (capital letter or small letters) reading]
- The 1D / 2D code reading function is compatible with the following code types and can read up to 80 characters.
  1D code: 25 types (Industrial 2 of 5, EAN-13, Code 39, etc. *1)
  2D code: 2 types (Data Matrix ECC 200, QR Code)
- Capable of checking the 1D / 2D code reading result with that of reading the character string indicated with the code
- Equipped with a function to check the 2D code print quality (Compliant with ISO / IEC 15415)
- Capable of combination inspections using a variety of checker functions of **PV200** (Smart edge, etc.)
- The PLC communications function enables communications with PLC without programming (Ethernet and RS-232C).
- Compatible with setup software (**PVWIN230**), which enables off-line operation

## ◎ A wide variety of Preprocessing filters, Color extraction and Gray conversion functions provide reliable reading

Reliably extracting only characters of selected colors even if the contrast with the background is low (Characters of up to 8 colors can be extracted simultaneously.)



Capable of reliably reading deformed, distorted or partly chipped characters
Arc-shaped character strings, italic and dotted characters can be read.
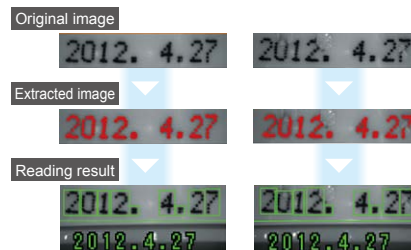


2D code reading: Codes with contrast fluctuations, out-of-focus codes, and codes with hidden or chipped portions can also be read.



*1: Readable 1D codes (all the 25 types) : Industrial 2 of 5, Interleaved 2 of 5, Codabar, Code39, Code93, Code128, EAN-13, EAN-13 Add-On 2, EAN-13 Add-On 5, EAN-8, EAN-8 Add-On 2, EAN-8 Add-On 5, UPC-A, UPC-A Add-On 2, UPC-A Add-On 5, UPC-E, UPC-E Add-On 2, UPC-E Add-On 5, PharmaCode, RSS-14 (GS1 Databar), RSS-14 Truncated (GS1 Databar Truncated), RSS-14 Stacked (GS1 Databar Stacked), RSS-14 Stacked Omnidirectional (GS1 Databar Stacked Omnidirectional), RSS Limited (GS1 Databar Limited), RSS Expanded (GS1 Databar Expanded)

## Application examples of PV230

### Optical character recognition and positioning applications

**Conventional problem**

Work-piece slippage caused printing misalignment, which led to failure to pass the shipping inspection process.

**Benefit by PV230**

By performing position adjustment during the printing process, more products can pass which equates to greater yields. Furthermore, optical character recognition can also be performed in the same process.
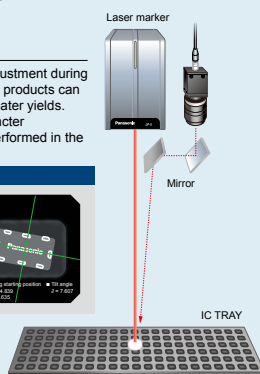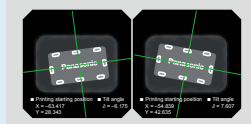


### Code reader, optical character recognition, stamp mark presence and external inspection applications

**Conventional problem**

It was necessary to control a machine vision system and a code reader in multiple steps by workers.

**Benefit by PV230**

The traceability can be done in one step, which makes automation possible. Furthermore, external inspection can also be performed in the same step.

Machine Vision System for Alignment

IMAGECHECKER  PV240

Model with alignment function
built into PV200

IMAGECHECKER
PV240

# Suggestion of Machine Vision System for Alignment

**Suggestion 1**  Auto calibration function

**Suggestion 2**  Calibration graphics

**Suggestion 3**  Alignment simulation function [setup software]

**Suggestion 4**  Sample setting data

Supported stages: UVW, XYθ, Xθ, XθY and YθX (also supports Line θ)

## ◉ Auto calibration function

The alignment mark is captured and the coordinates of the camera and stage are automatically calibrated.

**Settings are easy by using the sample setting data*!**
* Can be downloaded from our website.

**[Setting procedure]**

**1**  Calibration setting
• Stage setting  • Mark setting

**2**  Using auto calibration function
* The coordinates of camera and stage are automatically calibrated.

**No troublesome settings and calculations!**

Calibration complete

● The difference in two camera views and flexible camera attachment (rotation and tilt) also supported.

## ◉ Calibration graphics

Auto calibration result can be verified visually.
Easy to verify whether or not calibration was performed accurately, one of the factors for alignment problems.

Actual positional relationship

Camera 0          Camera 1

Camera 0 and camera 1 lateral placement

**Calibration good**

**Calibration not good**
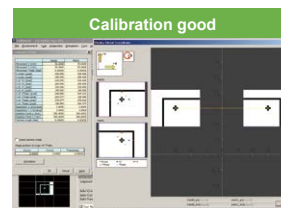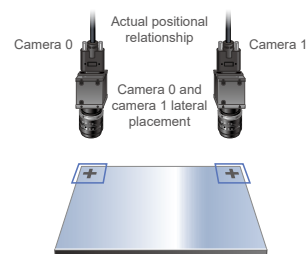
Auto calibration result:
**Lateral placement same as actual positional relationship**
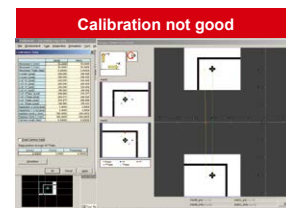
Auto calibration result:
**Vertical placement different from actual positional relationship**

## ◉ Alignment simulation function [setup software]   * Setup software can be downloaded from our website.

Alignment operation can be replicated on a PC.
The operation can be verified in stages through simulation that splits the alignment operation into 4 steps.

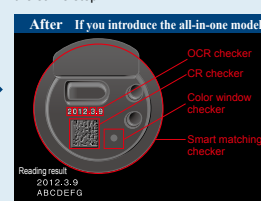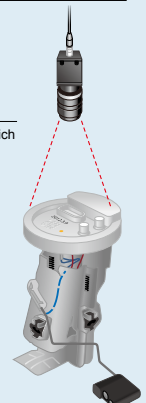**Step 1** Adjustment of rotation direction
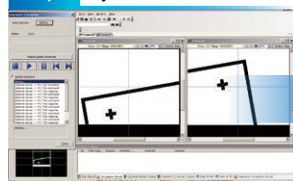
**Step 2** Adjustment of X-axis direction
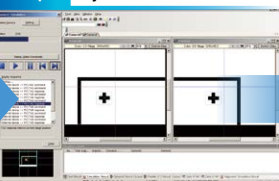
**Step 3** Adjustment of Y-axis direction
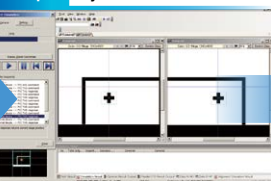
**Step 4** Alignment complete
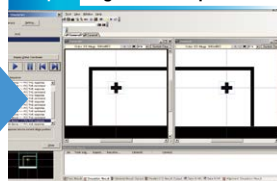
● In the event of a problem, as long as you have an image, you can use the setup software to check the alignment operation at your desk. This is convenient for determining the location of the source of the problem.

● By being able to check the output values, you can tell whether the problem is caused by image processing or whether it originates in the device.

## ◉ Sample setting data

* Sample setting data can be downloaded from our website.

Sample setting data saved with basic alignment conditions is available. Default settings are easily created by changing conditions such as the marks used by the user.

### Application examples of **PV240**

**Applying LCD and film**

**Crimping LCD and film boards**
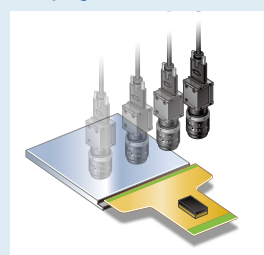
**IC tray positioning**

R o b o t   V i s i o n

IMAGECHECKER  PV260

Model with dedicated robot functions
built into PV200

IMAGECHECKER
PV260

# Robot setup made totally simple! Introducing true robot vision

## 4 functions reduce robot setup time.

## 1 Auto calibration function

**Man-hour reduction**   **Accuracy improvement**

By simply registering 3 or 4 capture coordinates with the **PV260**, you can easily convert the camera's coordinate system to the robot's coordinate system.
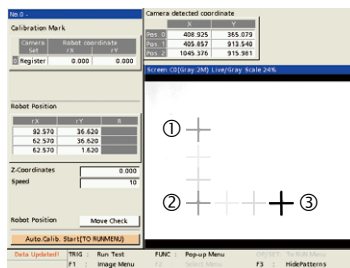
**Advantage**

1 Easier than doing it manually, work time is also reduced.

2 Even camera positional deviation can be quickly restored.

3 Variance in accuracy due to individual differences is eliminated.

## 2 Teaching support function

**Man-hour reduction**   **Accuracy improvement**

Improving on previous teaching operations that were carried out while manipulating a dedicated robot pendant, robot teaching can now be done on the **PV260** setup screen while viewing the captured image. Intuitive teaching can now be achieved using keypad operation.

- Teaching skill not required.
- Convenient in locations where teaching was difficult
- Increased safety
- Burden of repeated teaching reduced.

## 3 Robot tool offset function

**Man-hour reduction**   **Accuracy improvement**
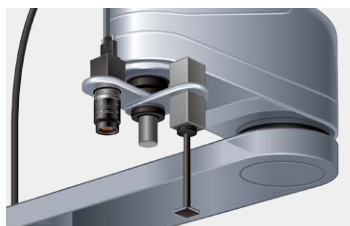
By simply registering two coordinates for the tool installed on the robot, the tool's coordinate system can be automatically calculated and converted to the robot's coordinate system.
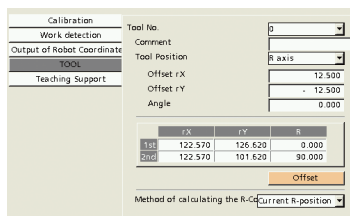
## 4 Direct communication function

**Man-hour reduction**
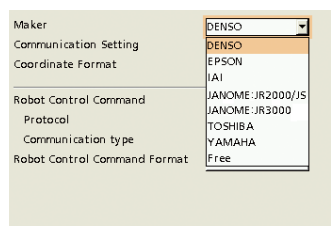
Direct communication is possible with different manufacturer's robot. PLC programming time can be reduced, because communication can be achieved by simply selecting the robot maker and type.
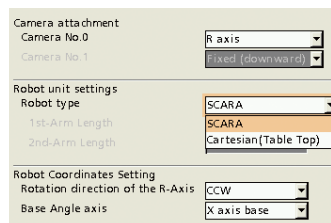
### Robot can be operated from keypad.

Robot can be moved using keypad operation. Adjustment of capture position is easy with features such as auto calibration and teaching support.

### PVWIN260 setup software

Robot vision inspection result can be replicated on a PC.
The continuous simulation and data logging functions facilitate setting data creation, corrections and verifications.

# System Configuration

Equipped with a full selection of interfaces essential for image processing devices of the future

SD memory card (SDHC compatible)

Keypad

Serial (RS-232C)

Parallel I/O
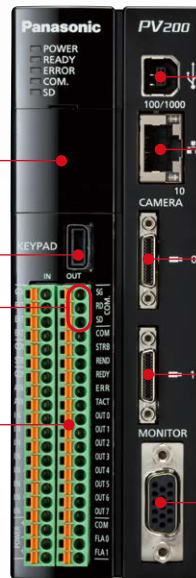
USB2.0

Gigabit Ethernet connector

Cameras (Digital cameras)
Up to two cameras of two different types can be connected.

0.3M color camera
0.3M color compact camera
2M color camera

0.3M grey camera
0.3M grey compact camera
2M grey camera
4M grey camera

*The 4M camera cannot be used in combination with another type of camera.

Analog RGB output

XGA monitor

# Product List

## Controller unit / Cameras / Keypads / Monitor / Camera attachment bracket

### IMAGECHECKER Controller unit

Machine Vision System
**PV200**
ANPV0202ADP

**PV200 MC**
ANPV0202MC

**PV230**
ANPV0232ADP

Machine Vision System for Alignment
**PV240**
ANPV0242ADP

Robot Vision
**PV260**
ANPV0262ADP

### Digital cameras for PV200 series

0.3M color camera (Quad-speed)
ANPVC2040

0.3M color compact camera (Triple-speed)
ANPVC6030

2M color camera
ANPVC2260

0.3M grey camera (Quad-speed)
ANPVC1040

0.3M grey compact camera (Triple-speed)
ANPVC5030

2M grey camera
ANPVC1210

4M grey camera
ANPVC1470

### Keypads

3 m 9.8 ft type:
ANPVP03

10 m 32.8 ft type:
ANPVP10

### Camera cables for PV200 series

3 m 9.8 ft type:
ANPVC8103

5 m 16.4 ft type:
ANPVC8105 *2

10 m 32.8 ft type:
ANPVC8110 *2

### Cable for PV200 series compact camera (for ANPVC5030 / ANPVC6030)

3 m 9.8 ft type:
ANPVC8203

5 m 16.4 ft type:
ANPVC8205

10 m 32.8 ft type:
ANPVC8210

### Flexible camera cables

3 m 9.8 ft type:
ANPVC8103R

5 m 16.4 ft type:
ANPVC8105R *2

10 m 32.8 ft type:
ANPVC8110R *2

### 0.3M camera lenses

f = 6 with lock
ANB842NL

f = 8.5 with lock
ANB843L *1

f = 16 with lock
ANB845NL

f = 16 with lock
ANM88161 *1

f = 25 with lock
ANB846NL

### 0.3M camera lenses

f = 25 with lock
ANM88251 *1

f = 50 with lock
ANB847L

f = 50 with lock
ANM88501

### 2-megapixel camera lenses

f = 16 with lock
ANPVL162

f = 25 with lock
ANPVL252

f = 50 with lock
ANPVL502

### Adapter rings (for the 0.3M cameras and 2-megapixel cameras)

5 mm 0.20 in x 1 ring
ANB84805

40, 20, 10, 5, 1, 0.5 mm 1.57, 0.79, 0.39, 0.20, 0.04, 0.02 in x 1 ring
ANB848

## Digital power supply units for LED lighting

### XGA monitor

10.4 inches
ANPVM11021

### Monitor cables

3 m 9.8 ft type:
ANMX83313

5 m 16.4 ft type:
ANMX83315

### Camera attachment bracket (For 4M grey camera)

ANPVH005

### Digital power supply units for LED lighting

10 W
ANB86001

30 W
ANB86003

*1 It can not be used in combination with the 0.3M compact camera.
*2 It can not be used in combination with the 4M grey camera.

# Dimensions (Unit: mm in)

## Controller unit / Monitor / Cameras / Keypads

◉ **Controller unit** ANPV0202ADP / ANPV0202MC / ANPV0232ADP / ANPV0242ADP / ANPV0262ADP
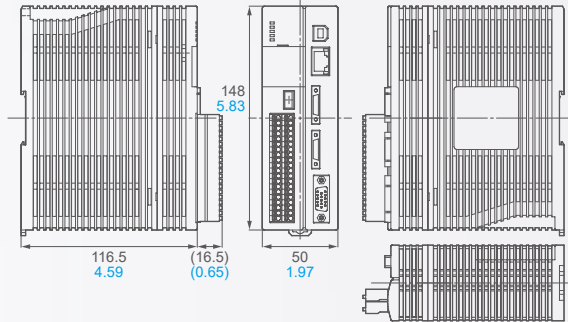
◉ **0.3M color and grey cameras** ANPVC2040 / ANPVC1040
◉ **2M color and grey cameras** ANPVC2260 / ANPVC1210
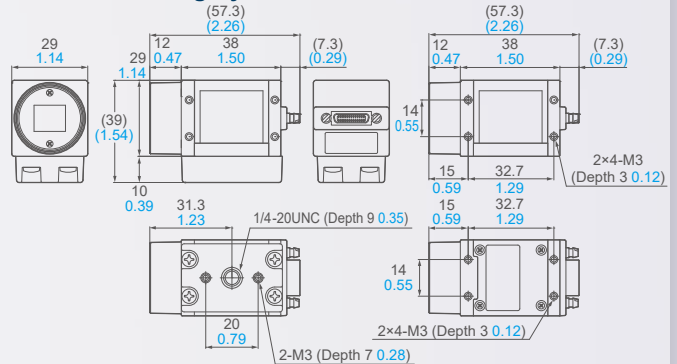
◉ **XGA monitor** ANPVM11021
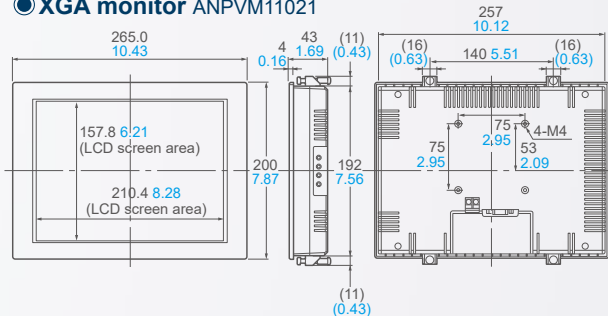
◉ **0.3M color and grey compact camera** ANPVC6030 / ANPVC5030
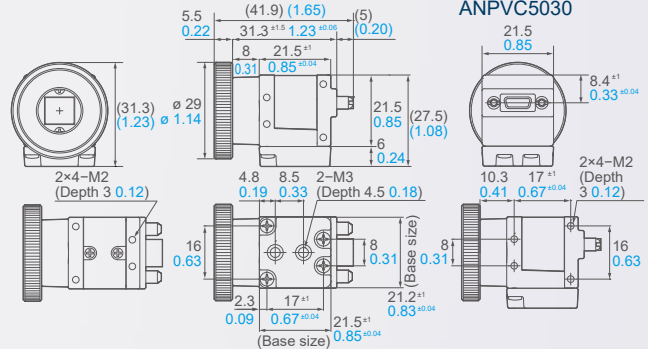
◉ **Operation keypad** ANPVP□
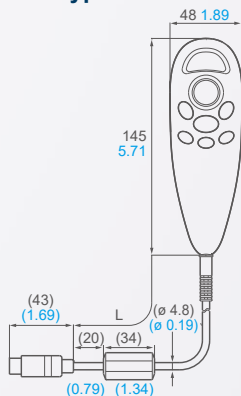
◉ **4M grey camera** ANPVC1470
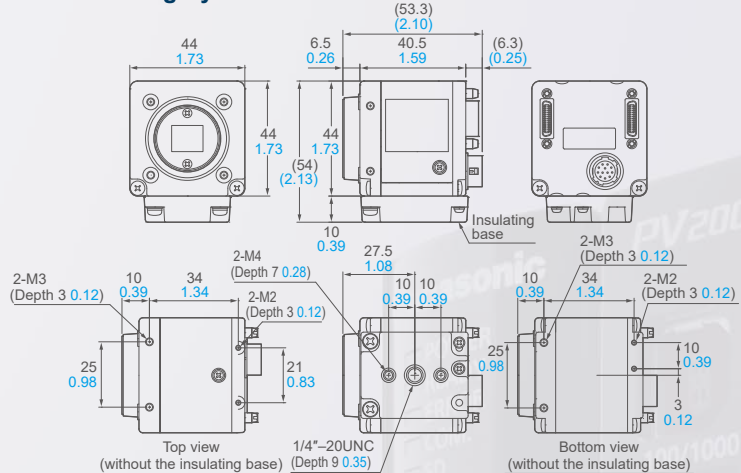
◉ **Lenses for camera** (Unit: mm in)

| | 0.3M camera lenses *2 | | | | | | | | 2-megapixel camera lenses | | |
|---|---|---|---|---|---|---|---|---|---|---|---|
| | f = 6 | f = 8.5 | f = 16 | | f = 25 | | f = 50 | | f = 16 | f = 25 | f = 50 |
| | ANB842NL | ANB843L | ANB845NL | ANM88161 | ANB846NL | ANM88251 | ANB847NL | ANM88501 | ANPVL162 | ANPVL252 | ANPVL502 |
| F-number | 1.2 | 1.5 | 1.4 | 1.4 | 1.4 | 1.6 | 1.4 | 2.8 | 1.4 | 1.4 | 2.8 |
| Ø A | 42 1.65 | 42 1.65 | 31 1.22 | 30.5 1.20 | 31 1.22 | 30.5 1.20 | 48 1.89 | 30.5 1.20 | 34 1.34 | 34 1.34 | 34 1.34 |
| L | 46 1.81 | 40 1.58 | 33 1.30 | 31.21 1.23 | 37.3 1.47 | 31.5 1.24 | 48 1.89 | 38.5 1.52 | 35.9 to 38.0 1.41 to 1.50 | 47.1 to 52.2 1.85 to 2.06 | 63.0 to 77.4 2.48 to 3.05 |
| B | – *1 | – *1 | – *1 | 21 0.83 | – *1 | 21 0.83 | – *1 | 21 0.83 | 22.5 0.89 | 22.5 0.89 | 22.5 0.89 |
| C | – *1 | – *1 | – *1 | 19.8 0.78 | – *1 | 20.05 0.79 | – *1 | 20.6 0.81 | 22 0.87 | 22 0.87 | 22 0.87 |

*1: The projection of the lock screw (M1.4 pan-head machine screw) is a maximum of 2 mm 0.08 in.
*2: ANB843L, ANM88161 and ANM88251 can not be used in combination with the 0.3M grey compact camera.

◉ **Camera attachment bracket (For 4M grey camera)** ANPVH005
Please refer to our website.

## Digital power supply units for LED lighting

◉ **Digital power supply units for LED lighting** ANB86001 / ANB86003

# Product Lineup

| Function item | PV200 | PV200 MC | PV230 |
|---|---|---|---|
| Controller unit | Color and greyscale combination<br>Image processing with top-level accuracy in its class is available with a surprisingly small number of man-hours required for programming. | High speed processing<br>0.3M compact limited edition special value camera with all the functions of the **PV200**. | Code reader and Optical character recognition<br>All-in-one model featuring image processing, optical character recognition (OCR) and code reading (CR) functions |
| Maximum connectable number of cameras | 2 | 2 | 2 |

**Camera**

| | PV200 | PV200 MC | PV230 |
|---|---|---|---|
| Pixel | Color: 0.3M compact / 0.3M / 2M　Grey: 0.3M compact / 0.3M / 2M / 4M | Color: 0.3M compact　Grey: 0.3M compact / 0.3M | Color: 0.3M compact / 0.3M / 2M　Grey: 0.3M compact / 0.3M / 2M / 4M |
| Grey/Color | Color / Grey | Color / Grey | Color / Grey |
| Shutter speed | 30 µs to 1,000 ms (Set in increments of 10 µs)<br>100 µs to 500 ms<br>(Set in increments of 10 µs, 0.3M compact type only) | 100 µs to 500 ms (Set in increments of 10 µs) | 30 µs to 1,000 ms (Set in increments of 10 µs)<br>100 µs to 500 ms<br>(Set in increments of 10 µs, 0.3M compact type only) |
| Monitor output | Analog RGB | Analog RGB | Analog RGB |
| Processing methods | Color, Greyscale, Binary | Color, Greyscale, Binary | Color, Greyscale, Binary |
| Maximum registerable number of product types *1 | 256 types | 256 types | 256 types |
| Maximum settable number of checkers *1 | 1,000 checkers/product type max. | 1,000 checkers/product type max. | 1,000 checkers/product type max. |

**Major inspection functions (Checkers)　○: Applicable model**

| Function | PV200 | PV200 MC | PV230 |
|---|---|---|---|
| Position adjustment / Position rotation adjustment | ○ | ○ | ○ |
| Area size adjustment | ○ | ○ | ○ |
| Binary window / Binary edge | ○ | ○ | ○ |
| Feature extraction | ○ | ○ | ○ |
| Grey window / Grey edge | ○ | ○ | ○ |
| Smart matching | ○ | ○ | ○ |
| Contour matching | ○ | ○ | ○ |
| Flaw detection | ○ | ○ | ○ |
| Connector (binary window, grey window, grey edge) | ○ | ○ | ○ |
| Smart edge (circles) / (line) | ○ | ○ | ○ |
| Geometry calculation | ○ | ○ | ○ |
| Character / Figure drawing | ○ | ○ | ○ |
| Dedicated function | | | Optical Character Recognition (OCR) and 1D / 2D Code Reading (CR) |
| Numerical calculation / Judgment output | 1,000 formula/product type max. | 1,000 formulas/product type max. | 1,000 formula/product type max. |
| Data R/W | 160 data | 160 data | 160 data |

**Execution mode**

| | PV200 | PV200 MC | PV230 |
|---|---|---|---|
| Execution all | Execution of all checkers | Execution of all checkers | Execution of all checkers |
| Branch execution | 0 to 9 can be set. | 0 to 9 can be set. | 0 to 9 can be set. |
| Designated execution | 0 to 9 can be set. | 0 to 9 can be set. | 0 to 9 can be set. |
| Password protection | ○ (Select menu) | ○ (Select menu) | ○ (Select menu) |
| Image preprocess / Image conversion | Preprocessing filters: 21 types, for each product type 16 groups/camera, 10 stages max. | Preprocessing filters: 21 types, for each product type 16 groups/camera, 10 stages max. | Preprocessing filters: 21 types, for each product type 16 groups/camera, 10 stages max. |
| Others | | | |

**Interface**

| | PV200 | PV200 MC | PV230 |
|---|---|---|---|
| RS-232C | 1 port | 1 port | 1 port |
| Ethernet | ○ | ○ | ○ |
| SD / SDHC | ○ | ○ | ○ |
| USB | ○ | ○ | ○ |
| Parallel input / output | 14 inputs, 15 outputs | 14 inputs, 15 outputs | 14 inputs, 15 outputs |
| Setup software | PVWIN200 | PVWIN200 | PVWIN230 |
| Recommended monitor (cable) | ANPVM11021 (ANMX83313) | ANPVM11021 (ANMX83313) | ANPVM11021 (ANMX83313) |

*1: Depend on the setting data size.

| | PV240 | PV260 | PV500V2 | PD60 / PD65 |
|---|---|---|---|---|
| | Alignment | Robot Vision | High speed, high productivity | 2D Code Reading Sensor |
| | Alignment functions are built in, such as the "Auto calibration function" and "Alignment simulation function". | 4 dedicated robot functions are built in. This not only increases productivity, but achieves a great reduction in the man-hours in robot prepping, maintenance, and product type changeovers. | "4 + 1" Penta processor enables extremely fast parallel processing. Verification of NG (failed) images and program corrections are possible while inspecting all items without stopping the production line. | Compliant with international standards Featuring a "2D code print quality verification function" |
| | 2 | 2 | 4 | 1 |
| | 0.3M compact / 0.3M / 2M | 0.3M compact / 0.3M / 2M / 4M | 0.3M compact / 0.3M / 2M | 0.1M |
| | Color / Grey | Color / Grey | Grey | Grey |
| | 30 µs to 1,000 ms (Set in increments of 10 µs) 100 µs to 500 ms (Set in increments of 10 µs, 0.3M compact type only) | 30 µs to 1,000 ms (Set in increments of 10 µs) 100 µs to 500 ms (Set in increments of 10 µs, 0.3M compact type only) | 30 µs to 1,000 ms (Set in increments of 10 µs) | 30 µs to 50 ms |
| | Analog RGB | Analog RGB | Analog RGB | — |
| | Color, Greyscale, Binary | Color, Greyscale, Binary | Greyscale, Binary | Binary |
| | 256 types | 256 types | 25,600 types | 7 types |
| | 1,000 checkers/product type max. | 1,000 checkers/product type max. | 1,000 checkers/product type max. | 1 checker/product type |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | — |
| | ○ | ○ | — | — |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | — |
| | Auto calibration, Calibration graphics and Alignment simulation | Auto calibration, Teaching support, Robot tool offset, Direct communication, Optical character recognition and 2D code | | 2D code reading ● DataMatrix (ECC200) ● QR code ● Micro QR code |
| | 1,000 formula/product type max. | 1,000 formula/product type max. | 1,000 formula/product type max. | — |
| | 160 data | 160 data | 320 data | — |
| | Execution of all checkers | Execution of all checkers | Execution of all checkers | Execution of all checkers |
| | 0 to 9 can be set. | 0 to 9 can be set. | 0 to 9 can be set. | — |
| | 0 to 9 can be set. | 0 to 9 can be set. | 0 to 9 can be set. | With retry function |
| | ○ (Select menu) | ○ (Select menu) | ○ | — |
| | Preprocessing filters: 21 types, for each product type 16 groups/camera, 10 stages max. | Preprocessing filters: 21 types, for each product type 16 groups/camera, 10 stages max. | Preprocessing filters: 21 types, for each product type 5 groups/camera, 10 stages max. | Preprocessing filters: 14 types, 10 stages max. |
| | | | Program editing/testing in RUN mode | Integrated lens and lighting unit, Protective construction: IP67G Stationary type: PD60, Handy type: PD65 |
| | 1 port | 1 port | 1 port | 1 port |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | — |
| | ○ | ○ | ○ | ○ |
| | 14 inputs, 15 outputs | 14 inputs, 15 outputs | PHOENIX terminal: 14 inputs, 15 outputs MIL terminal: 32 inputs, 32 outputs | 2 inputs, 3 outputs |
| | PVWIN240 | PVWIN260 | PVWIN | PDTOOL |
| | ANPVM11021 (ANMX83313) | ANPVM11021 (ANMX83313) | ANPVM11021 (ANMX83313) | — |

# Part No. List

## Controller units

| Product Name | Specification | Part No. |
|---|---|---|
| PV200 | PhotoMOS relay output, 2-camera type | ANPV0202ADP |
| PV200 MC | PhotoMOS relay output, 2-camera type | ANPV0202MC |
| PV230 | PhotoMOS relay output, 2-camera type | ANPV0232ADP |
| PV240 | PhotoMOS relay output, 2-camera type | ANPV0242ADP |
| PV260 | PhotoMOS relay output, 2-camera type | ANPV0262ADP |
| PV500V2 | NPN output, 2-camera type | ANPV0502V2ADN |
| PV500V2 | PhotoMOS relay output, 2-camera type | ANPV0502V2ADP |
| PV500V2 | NPN output, 4-camera type | ANPV0504V2ADN |
| PV500V2 | PhotoMOS relay output, 4-camera type | ANPV0504V2ADP |
| 2D Code reading sensor PD60 | Field of view: 2 × 1.6 mm 0.08 × 0.06 in, Installation distance: 15±0.5 mm 0.59±0.02 in | ANPD060-02 |
| 2D Code reading sensor PD60 | Field of view: 4 × 3.2 mm 0.16 × 0.13 in, Installation distance: 50±2.5 mm 1.97±0.10 in | ANPD060-04 |
| 2D Code reading sensor PD60 | Field of view: 5 × 4 mm 0.20 × 0.16 in, Installation distance: 27±1.0 mm 1.06±0.04 in | ANPD060-05 |
| 2D Code reading sensor PD60 | Field of view: 6 × 4.8 mm 0.24 × 0.19 in, Installation distance: 30±1.5 mm 1.18±0.06 in | ANPD060-06 |
| 2D Code reading sensor PD60 | Field of view: 10 × 8 mm 0.39 × 0.32 in, Installation distance: 100±5.0 mm 3.94±0.20 in | ANPD060-10 |
| 2D Code reading sensor PD60 | Field of view: 10 × 8 mm 0.39 × 0.32 in, Installation distance: 45±2.0 mm 1.77±0.08 in | ANPD060S10 |
| 2D Code reading sensor PD60 | Field of view: 12 × 10 mm 0.47 × 0.39 in, Installation distance: 110±5.5 mm 4.33±0.22 in | ANPD060-12 |
| 2D Code reading sensor PD60 | Field of view: 15 × 12 mm 0.59 × 0.47 in Installation distance: 65±3.0 mm 2.56±0.12 in | ANPD060-15 |
| 2D Code reading sensor PD60 | Field of view: 20 × 16 mm 0.79 × 0.63 in Installation distance: 80±4.0 mm 3.15±0.16 in | ANPD060-20 |
| 2D Code reading sensor PD60 | Field of view: 25 × 20 mm 0.98 × 0.79 in Installation distance: 200±10 mm 7.78±0.39 in | ANPD060-25 |
| 2D Code reading sensor PD60 | Field of view: 25 × 20 mm 0.98 × 0.79 in Installation distance: 105±5 mm 4.13±0.20 in | ANPD060S25 |
| 2D Code reading sensor PD60 | Field of view: 30 × 25 mm 1.18 × 0.98 in Installation distance: 55±2.5 mm 2.17±0.10 in | ANPD060-30 |
| 2D Code reading sensor PD65 | Field of view: 12 × 10 mm 0.47 × 0.39 in, Installation distance: Contact type | ANPD065-12 |
| 2D Code reading sensor PD65 | Field of view: 25 × 20 mm 0.98 × 0.79 in, Installation distance: Contact type | ANPD065-25 |

## Cameras and Camera cables  ○: Applicable model

| Product Name | Specification | Part No. | PV200 | PV200 MC | PV230 | PV240 | PV260 | PV500V2 | PD60/PD65 |
|---|---|---|---|---|---|---|---|---|---|
| 0.3M Color camera | 0.3M | ANPVC2040 | ○ | | ○ | ○ | ○ | | |
| 0.3M Color compact camera | 0.3M | ANPVC6030 | ○ | ○ | ○ | ○ | ○ | | |
| 2M Color camera | 2M | ANPVC2260 | ○ | | ○ | ○ | ○ | | |
| 0.3M Grey camera | 0.3M | ANPVC1040 | ○ | | ○ | ○ | ○ | ○ | |
| 0.3M Grey compact camera | 0.3M | ANPVC5030 | ○ | ○ | ○ | ○ | ○ | ○ | |
| 2M Grey camera | 2M | ANPVC1210 | ○ | | ○ | ○ | ○ | ○ | |
| 4M Grey camera | 4M | ANPVC1470 | ○ | | ○ | ○ | ○ | | |
| Camera cable | 3 m 9.8 ft | ANPVC8103 | ○ | | ○ | ○ | ○ | ○ | |
| Camera cable | 5 m 16.4 ft *1 | ANPVC8105 | ○ | | ○ | ○ | ○ | ○ | |
| Camera cable | 10 m 32.8 ft *1 | ANPVC8110 | ○ | | ○ | ○ | ○ | ○ | |
| Camera cable | Flexible 3 m 9.8 ft | ANPVC8103R | ○ | | ○ | ○ | ○ | ○ | |
| Camera cable | Flexible 5 m 16.4 ft *1 | ANPVC8105R | ○ | | ○ | ○ | ○ | ○ | |
| Camera cable | Flexible 10 m 32.8 ft *1 | ANPVC8110R | ○ | | ○ | ○ | ○ | ○ | |
| Camera cable | For compact camera 3 m 9.8 ft | ANPVC8203 | ○ | ○ | ○ | ○ | ○ | ○ | |
| Camera cable | For compact camera 5 m 16.4 ft | ANPVC8205 | ○ | ○ | ○ | ○ | ○ | ○ | |
| Camera cable | For compact camera 10 m 32.8 ft | ANPVC8210 | ○ | ○ | ○ | ○ | ○ | ○ | |

*1 It can not be used in combination with the 4M grey camera (ANPVC1470).

## Keypads  ○: Applicable model

| Product Name | Specification | Part No. | PV200 | PV200 MC | PV230 | PV240 | PV260 | PV500V2 | PD60/PD65 |
|---|---|---|---|---|---|---|---|---|---|
| Keypad | 3 m 9.8 ft, CE product | ANPVP03 | ○ | ○ | ○ | ○ | ○ | ○ | |
| Keypad | 10 m 32.8 ft, CE product | ANPVP10 | ○ | ○ | ○ | ○ | ○ | ○ | |

## Lens   ○: Applicable model

| Product Name | Specification | Part No. | PV200 | PV200 MC | PV230 | PV240 | PV260 | PV500V2 | PD60/PD65 |
|---|---|---|---|---|---|---|---|---|---|
| For 0.3M camera | f=6 C mount lens with lock | ANB842NL | ○ | ○ | ○ | ○ | ○ | ○ | |
| | f=8.5 C mount lens with lock | ANB843L | ○ *1 | | ○ *1 | ○ *1 | ○ *1 | ○ | |
| | f=16 C mount compact lens with lock | ANB845NL | ○ | ○ | ○ | ○ | ○ | ○ | |
| | f=25 C mount compact lens with lock | ANB846NL | ○ | ○ | ○ | ○ | ○ | ○ | |
| | f=50 C mount lens with lock | ANB847L | ○ | ○ | ○ | ○ | ○ | ○ | |
| | f=16 C mount ultra compact lens with lock | ANM88161 | ○ *1 | | ○ *1 | ○ *1 | ○ *1 | ○ | |
| | f=25 C mount ultra compact lens with lock | ANM88251 | ○ *1 | | ○ *1 | ○ *1 | ○ *1 | ○ | |
| | f=50 C mount compact lens with lock | ANM88501 | ○ | ○ | ○ | ○ | ○ | ○ | |
| For 2-megapixel camera | f=16 C mount lens with lock | ANPVL162 | ○ | | ○ | ○ | ○ | ○ | |
| | f=25 C mount lens with lock | ANPVL252 | ○ | | ○ | ○ | ○ | ○ | |
| | f=50 C mount lens with lock | ANPVL502 | ○ | | ○ | ○ | ○ | ○ | |

*1 It can not be used in combination with the 0.3M grey compact camera.

## Adapter rings   ○: Applicable model

| Product Name | Specification | Part No. | PV200 | PV200 MC | PV230 | PV240 | PV260 | PV500V2 | PD60/PD65 |
|---|---|---|---|---|---|---|---|---|---|
| C mount | Ring set (40/20/10/5/1/0.5 mm 1.58/0.79/0.39/0.20/0.04/0.02 in, each 1 pc.) | ANB848 | ○ | ○ | ○ | ○ | ○ | ○ | |
| | 5 mm 0.20 in adapter ring, 1pc. | ANB84805 | ○ | ○ | ○ | ○ | ○ | ○ | |

## Monitors and Monitor cables   ○: Applicable model

| Product Name | Specification | Part No. | PV200 | PV200 MC | PV230 | PV240 | PV260 | PV500V2 | PD60/PD65 |
|---|---|---|---|---|---|---|---|---|---|
| XGA monitor | 24 V DC, 10.4 inches | ANPVM11021 | ○ | ○ | ○ | ○ | ○ | ○ | |
| For XGA monitor | Monitor cable: 3 m 9.8 ft | ANMX83313 | ○ | ○ | ○ | ○ | ○ | ○ | |
| | Monitor cable: 5 m 16.4 ft | ANMX83315 | ○ | ○ | ○ | ○ | ○ | ○ | |

## Others   ○: Applicable model

| Product Name | Specification | Part No. | PV200 | PV200 MC | PV230 | PV240 | PV260 | PV500V2 | PD60/PD65 |
|---|---|---|---|---|---|---|---|---|---|
| Attachment bracket | 4 attachment bracket for 4M grey camera | ANPVH005 | ○ | | ○ | ○ | ○ | | |
| | For mounting PD60 | ANE8870 | | | | | | | ○ |
| Options (repair parts) | Set with PD65 guide pipe, packing, and stop screws | ANPD068-G1 | | | | | | | ○ |
| | Set with PD65 guide pipe (short pipe type), packing, and stop screws | ANPD068-G2 | | | | | | | ○ |
| | Power supply I/O cable (2,700 mm 106.30 in) for PD60 / PD65 | ANPD068-K1 | | | | | | | ○ |
| | Set with PD60 front panel, packing, and stop screws | ANPD068-P1 | | | | | | | ○ |
| | Set with PD60 front panel (narrow view type), packing, and stop screws | ANPD068-P2 | | | | | | | ○ |
| Extension cables | 3 m 9.8 ft for PD60 / PD65 | ANPD068-03 | | | | | | | ○ |
| | 5 m 16.4 ft for PD60 / PD65 | ANPD068-05 | | | | | | | ○ |
| | 10 m 32.8 ft for PD60 / PD65 | ANPD068-10 | | | | | | | ○ |
| RS-232C communication cable | For PLC (discrete-wire cable) connection, 2 m 6.6 ft | AIP81842 | | | | | | ○ | |
| | For PC (D-SUB : 9 pin) connection, 3 m 9.8 ft | AFB85853 | | | | | | ○ | |

# Specifications

## General specifications

| Item | Specifications |
|---|---|
| Rated operating voltage | 24 V DC |
| Operating voltage range | 21.6 to 26.4 V DC (including ripples) |
| Rated current consumption | 1.2 A max. |
| Ambient temperature during use | 0 to +45 °C 32 to +113 °F (However, no condensation or no freezing) |
| Storage ambient temperature | -20 to +60 °C -4 to +140 °F (However, no condensation or no freezing) |
| Ambient humidity during use | 35 to 85 % RH (at 25 °C 77 °F, However, no condensation or no freezing) |
| Storage ambient humidity | 35 to 85 % RH (at 25 °C 77 °F, However, no condensation or no freezing) |
| Noise immunity | 1,000 V, Pulse width: 50 ns, 1 µs (using the noise simulator method) |
| Vibration resistance | 10 to 55 Hz, 1 sweep/min, double amplitude of 0.75 mm 0.03 in, 30 minutes each in the X, Y, and Z directions |
| Shock resistance | 196 m/s², 5 times each in the X, Y and Z directions |
| Insulation resistance (initial value) | 100 MΩ or higher (measured by a 500 V DC megger) *1 |
| | Input and output terminals -- Power and ground terminals |
| | Input and output terminals -- Non-energized metal part |
| | Power terminal -- Non-energized metal part |
| Breakdown voltage (initial value) | 500 V AC for 1 min (600 V AC for 1 sec), Cutoff current: 10 mA *1 |
| | Input and output terminals -- Power and ground terminals |
| | Input and output terminals -- Non-energized metal part |
| | Power terminal -- Non-energized metal part |
| Battery life | 10 years approx. (at 25 °C 77 °F) |
| Weight | 0.5 kg approx. (including terminal blocks) |
| Pollution degree | 2 |

*1: The evaluation was carried out with the primary side power supply varistor and capacitor removed from the internal circuit of the unit.

## Functional specifications

| Item | Specifications | |
|---|---|---|
| CPU | 32-bit, RISC CPU & DSP | |
| Input/output — Cameras | Up to two cameras selected from among 0.3M grey/grey compact/color cameras (640 x 480), 0.3M color compact camera (640 x 478) and 2M grey/color cameras (1,600 x 1,200) can be connected. Up to two 4M grey cameras can be connected. *2 | |
| Monitor output | Analog RGB (640 x 480) output | |
| Memory card | SD/SDHC memory card | |
| PLC communication compatible models (RS-232C) | Panasonic Industrial Devices SUNX | FP series |
| | OMRON | C, CV, and CS1 series |
| | Mitsubishi Electric | A, Q, FX, and FX2N series |
| | Fuji Electric | MICREX-SX SPH series |
| | Allen-Bradley | SLC500 series |
| | Modbus RTU compatible (performance confirmed with Siemens S7-1200) | |
| PLC communication compatible models (Ethernet) | Panasonic Industrial Devices SUNX | FP series, ET-LAN unit |
| | Mitsubishi Electric | Q series |
| | Yokogawa Electric | FA-M3 series |
| PLC communication command | Specifiable external command instruction using PLC communication   Command input format: polling / parallel input | |
| Parallel | 14 inputs / 15 outputs | |
| Keypad input | Connector for dedicated keypad (ANPVP**), 1 channel | |
| USB | USB 2.0, A-B type (Only PVWIN200) | |
| Menu display | Four languages (five fonts), Switchable (Japanese, English, Korean, Traditional Chinese and Simplified Chinese) | |
| Monitor display | Split-screen display of up to two camera images, Zoom function (2 to 400%) | |
| | Image display: Through/Memory/NG object images | |
| | Display effects: Greyscale/Slice level group/Preprocessing group/Color/Extraction and binary/Grey conversion image, Display area (640 x 480) | |
| Processing methods | Greyscale processing/Thresholding processin/Color extraction/Grey conversion | |
| Processing resolution | 2M camera (grey/color): 1,600 horizontal x 1,200 vertical pixels | |
| | 0.3M camera (grey/grey compact/color): 640 horizontal x 480 vertical pixels | |
| | 0.3M camera (color compact): 640 horizontal x 478 vertical pixels | |
| | 4M camera (grey): 2,048 horizontal x 2,048 vertical pixels | |
| Trigger input | Select from: All cameras or detection trigger | |
| Number of connected cameras | Up to two cameras | |
| Camera connection | Connection by Power Over Camera Link (PoCL) | |
| Capture method | Frame shooting only. Capable of partial capture of one point | |
| | In partial capture mode, the minimum capture area to be set for the 0.3M/4M camera is one line, and that for the 2M camera is 100 lines. (The area can be set in increments of one line for the grey camera, and two lines for the color camera.) | |
| Shutter speed | 30 µs to 1,000 ms (Set in increments of 10 µs) | |
| | However, 0.3M grey compact camera is 100µs to 500 ms (Set in increments of 10µs) | |
| Gain setting range | 1.0 to 5.0 | |
| Number of product types | 256 types max. (depends on setting data) | |
| Password | Switching from the current operating screen to the setup screen can be password controlled (within 15 characters). | |
| | Administration classification: invalid/valid (limit setting screen transition and limit regular menu switching) | |
| Inspection functions (Checkers) | 1,000 checkers/product type max., including those for geometry calculation and character/figure drawing (depends on setting data) | |
| | Position adjustment, Position rotation adjustment, Rotation adjustment area size adjustment, Line, Binary window, Grey window, Binary edge, Grey edge, Feature extraction, Smart matching, Contour matching, Flaw detection, Connector (binary window), Connector (grey window), Connector (grey edge), Smart edge (circles), Smart edge (line), Color window | |
| | * Number of range masks: 16 ranges/checker | |
| | * Maximum registrable number of smart matching and contour matching templates: 2,000 pcs. | |
| Geometry calculation | 1,000 checkers/product type max., including those for inspection functions and character/figure drawing (depends on setting data) | |
| | Eight calculation functions (distance between two points, intersection of two lines, median lines of two lines, perpendicular distance, approximate straight line, approximate circle, and approximate ellipse) | |
| Character/Figure drawing | Up to 10,000 characters/graphics (1,000 checkers x 10)/product type can be displayed on the images (depends on setting data). | |
| Inspection operation mode | Sequential processing: After completing the result output, the next image capture for inspection can be started. Parallel processing: After the capture and the synchronized output of results of the previous inspection are completed, the image capture process for the next inspection is ready to start, and then the capture and inspection results output are processed concurrently. | |
| Slice level group | 16 group/camera, 256-grey scale (0 to 255) | |

## Functional specifications

| Item | Specifications | |
|---|---|---|
| Image preprocess | Preprocessing selections: Grey conversion / Color extraction / Grey preprocessing | |
| | Grey conversion | Available only when a color camera is connected. For each product type, 16 groups/camera Each R/G/B value setting for grey conversion can be changed within the range of -1,000 to 1,000. |
| | Color extraction | Available only when a color camera is connected. Color extraction mode: Selectable between high speed and expansion |
| | | Number of extractable colors: High speed: A total of 16 colors when one camera is connected and eight colors when two cameras are connected. |
| | | Expansion: A total of 128 colors when one camera is connected and 64 colors when two cameras are connected. |
| | | Only eight registered colors can be selected from one checker. |
| | Grey preprocessing | For each product type, 16 groups/camera, 10 stages max. |
| | | Preprocessing filters: 21 types |
| | | (Dilation, Erosion, Erosion → Dilation, Dilation → Erosion, Auto correction, Grey cut, Area averaging, Correction settings, Median, Smoothing, Sobel, Prewitt, Laplacian, Edge extraction X, Edge extraction Y, Sharpen, Tophat, Dynamic, Grey difference, Rotation, and Reflect) |
| Numerical calculation | 1,000 formulas/product type max., including those for judgement output (depends on setting data) | |
| | Calculations involving output values of inspection functions | |
| | Operators | Four fundamental operations (+, -, x, ÷), Bracket operations, Trigonometric functions (14 types), Comparison functions (6 types), Math functions (15 types), Geometry functions (18 types), Coordinate conversion functions (8 types) |
| | Statistic data operation items | Scan count/OK count/NG count/Average/Variance/Max./Min./Range/OK average/ OK variance/OK judgment max./OK judgment min./OK range/NG average/NG variance/ NG judgment max./NG judgment min./NG range   User limit: 1,000 items /product type max. |
| | Other operation items | Previous data of numerical calculation and judgment results, general-purpose registers |
| | Number of reference operators | 16 items/formula max. |
| Judgement output | 1,000 formula/product type max., including those for numerical calculation (depends on setting data) | |
| | Substitution for and logical calculation of judgement results from checkers and numerical calculations | |
| | Operators | NOT/AND/OR/XOR/Brackets |
| | Number of reference items | 16 items/formula max. |
| | Others | Total judgment conditions, save image conditions, Image output conditions, parallel output setting (8 outputs from OUT0 to OUT7 and 16 outputs from OUT0 to OUT15, or all setting output) |
| Collective moving | Collective movement of set checkers in units of position/rotation adjustment groups | |
| | Specify the "Move" or "Not move" option for each checker type. | |
| | However, position and rotation adjustment checkers cannot be moved. | |
| Marker | 8 markers/product type max. for each camera, Graphic display on the operation screen, Selectable from six colors | |
| | Shapes | Rectangle/Circle, Ellipse/Polygon/Line/Cross |
| Data R/W | Two-window display of up to 80 (5x16) cells/product type on screen in table form in RUN mode | |
| | Substitution of title input, checker conditions/results, numerical calculation results, numerical calculation judgment results, judgment results, statistical results possible. Change of upper/lower limits of numerical computation in the table in RUN mode possible. | |
| Select menu | Maximum registrable number of arbitrary setup items in setup screen on menu: 16 items x 50 pages/type. | |
| | Registration information | Button / Text / Page move / Separator |
| | Button allocation method | FUNC key for item / Selection from list |
| | Others | Page name registration possible |
| Calibration | Coordinates, coordinate origin, horizontal and vertical coefficients can be set for each camera to obtain actual dimensions for each product type. | |
| | Processing method | Unit conversion / 1 point coordinate conversion / 2 point coordinate conversion / 3 points coordinate conversion |
| | Operation method | Static / Dynamic |
| | Standard registration | Arbitrary position / Smart matching / Contour matching / Intersection / Centre of circle / Feature extraction |
| Conversion data | Coordinates, coordinate origin, horizontal and vertical coefficients can be set for each camera to obtain actual dimensions. | |
| | Others | Comment input |
| Template re-registration settings | Position | Set position/Adjusted position |
| | Display | Yes/No |
| Execution mode | All execution | Execution of all checkers |
| | Branch execution | Destination blocks (0 to 9) can be set. |
| | Designated execution | Blocks to be executed (0 to 9) can be set. |

| ○: Applicable, ✕: Inapplicable | Parallel | Serial | Ethernet | SD memory card |
|---|---|---|---|---|
| **Input** | | | | |
| Inspection start instruction | ○ | ○ | ○ | — |
| Re-inspection start instruction | ○ | ○ | ○ | — |
| Product type change instruction | ○ | ○ | ○ | — |
| Template re-registration instruction | ○ | ○ | ○ | — |
| Display layout switch instruction | ○ | ○ | ○ | — |
| Operation/stop switch instruction | ○ | ○ | ○ | — |
| Statistics reset instruction | ○ | ○ | ○ | — |
| Error reset instruction | ○ | ○ | ○ | — |
| Instruction to save setting data in the built-in memory | ○ | ○ | ○ | — |
| Instruction to save setting data in the SD memory card | ○ | ○ | ○ | — |
| Instruction to read setting data from the built-in memory | ○ | ○ | ○ | — |
| Instruction to read setting data from the SD memory card | ○ | ○ | ○ | — |
| Instruction to cancel the saving/reading of setting data | ○ | ○ | ○ | — |
| Instruction to save the image memory in the SD memory card | ○ | ○ | ○ | — |
| Instruction to erase the image memory | ○ | ○ | ○ | — |
| Instruction to print the screenshot | ○ | ○ | ○ | — |
| Inspection/processing cancellation instruction | ○ | ○ | ○ | — |
| Instruction to save the latest inspection image | ○ | ✕ | ✕ | — |
| Instruction to read/change the set value | ✕ | ○ | ○ | — |
| Instruction to prohibit the keypad screen operation | ✕ | ○ | ○ | — |
| Keypad emulation instruction | ✕ | ○ | ○ | — |
| PLC communication command read instruction | ✕ | ✕ | ✕ | — |
| **Output** | | | | |
| Scanning operation count | ○ | ○ | ○ | ○ |
| Total judgement output | ○ | ○ | ○ | ○ |
| Judgement calculation (JD) result output | ○ | ○ | ○ | ○ |
| Numerical calculation result output | ○ | ○ | ○ | ○ |
| Image output | ✕ | ✕ | ○*4 | ○ |
| Screenshot output | ✕ | ✕ | ○*4 | ○ |

Specifications for PV200 firmware Ver. 1.5 or later.
*2: The 4M grey camera cannot be used in combination with another type of camera. The ANPVC82□ dedicated compact camera cable is required to connect the compact cameras.
*3: USB cannot be used for the external input/output functions.
*4: Image and screenshot output functions via Ethernet are received by dedicated software, Image Receiver for PV.
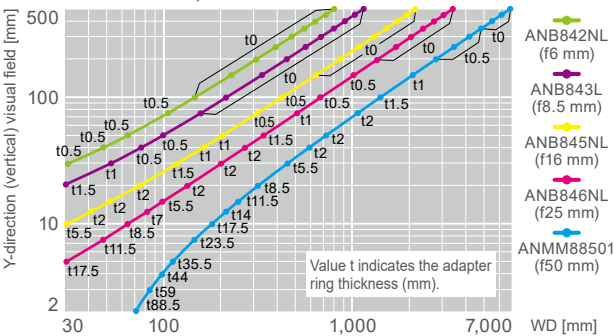
# Specifications

## Camera specifications

| Item | Specifications | | | | | | |
|---|---|---|---|---|---|---|---|
| Type/Part No. | 4M grey / ANPVC1470 | 2M grey / ANPVC1210 | 0.3M grey / ANPVC1040 | 0.3M color compact / ANPVC6030 | 0.3M grey compact / ANPVC5030 | 2M color/ANPVC2260 | 0.3M color/ANPVC2040 |
| Capture element | 2/3-inch CCD fixed image element | 1/1.8-inch CCD fixed image element | 1/3-inch CCD fixed image element | 1/3-inch CMOS fixed image element | 1/3-inch CMOS fixed image element | 1/1.8-inch CCD fixed image element | 1/3-inch CCD fixed image element |
| Pixels | 2,048 horizontal x 2,048 vertical pixels | 1,600 horizontal x 1,200 vertical pixels | 640 horizontal x 480 vertical pixels | 640 horizontal x 478 vertical pixels | 640 horizontal x 480 vertical pixels | 1,600 horizontal x 1,200 vertical pixels | 640 horizontal x 480 vertical pixels |
| | Pixel size: 3.45 µm x 3.45 µm | Pixel size: 4.4 µm x 4.4 µm | Pixel size: 7.4 µm x 7.4 µm | Pixel size: 6.0 µm x 6.0 µm | Pixel size: 6.0 µm x 6.0 µm | Pixel size: 4.4 µm x 4.4 µm | Pixel size: 7.4 µm x 7.4 µm |
| | (Square pixels) | (Square pixels) | (Square pixels) | (Square pixels) | (Square pixels) | (Square pixels) | (Square pixels) |
| Frame rate | 16 frames/sec max. | 30 frames/sec max. | 120 frames/sec max. | 90 frames/sec max. | 90 frames/sec max. | 30 frames/sec max. | 120 frames/sec max. |
| Lens mount | C mount | | | NF mount *2 | | C mount | |
| Ambient temperature during use *1 | 0 to +40 °C +32 to +104 °F | 0 to +40 °C +32 to +104 °F | 0 to +45 °C +32 to +113 °F | 0 to +40 °C +32 to +104 °F | 0 to +40 °C +32 to +104 °F | 0 to +40 °C +32 to +104 °F | 0 to +45 °C +32 to +113 °F |
| Ambient humidity during use *1 | 35 to 85% RH (at 25 °C 77 °F) | | | | | | |
| Vibration resistance | 10 to 55 Hz, 1 sweep/min, double amplitude of 1 mm 0.04 in, 30 minutes each in the X, Y, and Z directions | | 10 to 200 Hz, 1 sweep/10 min, 30 minutes each in the 3 directions | | | 10 to 55 Hz, 1 sweep/min, double amplitude of 1 mm 0.04 in, 30 minutes each in the X, Y, and Z directions | |
| Shock resistance | 490.3 m/s², 1 time each in the X, Y and Z directions | 700 m/s², 3 times each in the X, Y and Z directions | | 700 m/s², 1 time each in the X, Y and Z directions | | 700 m/s², 3 times each in the X, Y and Z directions | |
| Weight (Excluding the lens) | 125 g approx. | 65 g approx. | 65 g approx. | 30 g approx. | 30 g approx. | 65 g approx. | 65 g approx. |

*1: However, no condensation or no freezing   *2: Comes with C mount adapter.
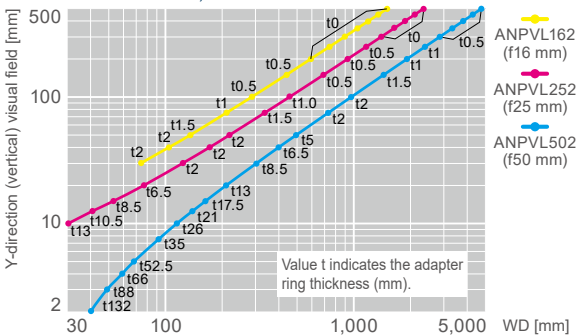
# Visual Fields

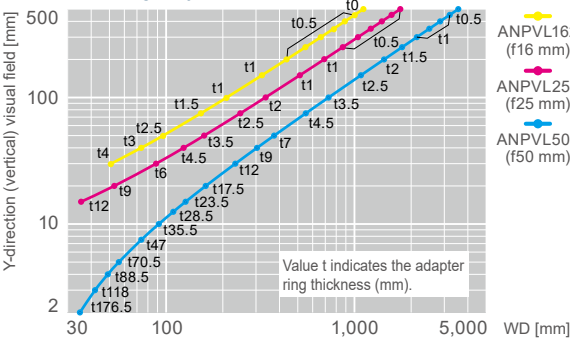### ● 0.3M color and grey camera
ANPVC2040, ANPVC1040



ANB842NL (f6 mm)
ANB843L (f8.5 mm)
ANB845NL (f16 mm)
ANB846NL (f25 mm)
ANMM88501 (f50 mm)

Value t indicates the adapter ring thickness (mm).

### ● 2M color and grey camera
ANPVC2260, ANPVC1210



ANPVL162 (f16 mm)
ANPVL252 (f25 mm)
ANPVL502 (f50 mm)

Value t indicates the adapter ring thickness (mm).

### ● 4M grey camera
ANPVC1470



ANPVL162 (f16 mm)
ANPVL252 (f25 mm)
ANPVL502 (f50 mm)

Value t indicates the adapter ring thickness (mm).

### ● 0.3M color and grey compact camera
ANPVC6030, ANPVC5030



ANB842NL (f6 mm)
ANB845NL (f16 mm)
ANB846NL (f25 mm)
ANM88501 (f50 mm)

Value t indicates the adapter ring thickness (mm).
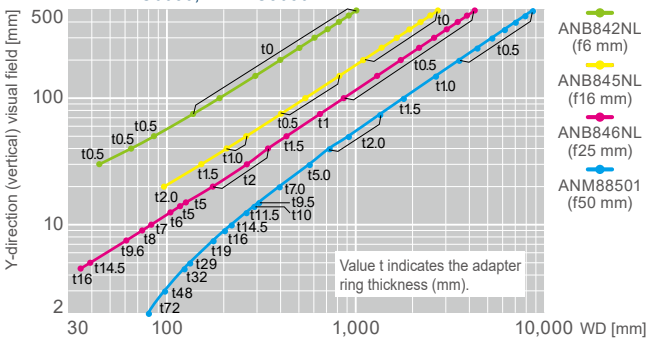
The X-direction (horizontal) visual field is the Y-direction visual field multiplied by 1.3.
* Please use these values as reference purposes only. Check the details with the **PV200** User's Manual.

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